

SAMPLE EXAM 2

SECTION A

1. Answer ALL parts of the question:

- (a) Determine the constant a such that the vectors $\mathbf{A} = 2\mathbf{i} + a\mathbf{j} + \mathbf{k}$ and $\mathbf{B} = 4\mathbf{i} - 2\mathbf{j} - 2\mathbf{k}$ are perpendicular.

(4 Marks)

- (b) Consider a body that rotates with constant angular velocity $\boldsymbol{\omega} = 4\mathbf{i} + 3\mathbf{j} - \mathbf{k}$. Calculate the tangential velocity $\mathbf{v} = \boldsymbol{\omega} \times \mathbf{r}$ at the point given by the position vector $\mathbf{r} = 2\mathbf{i} - 6\mathbf{j} - 3\mathbf{k}$.

(4 Marks)

- (c) Define $\text{div}\mathbf{V} = \nabla \cdot \mathbf{V}$, where $\mathbf{V} = \mathbf{V}(x, y, z)$ is a vector field. Describe, in words, what properties of the field \mathbf{V} are expressed by its *divergence*.

(5 Marks)

- (d) Define $\text{curl}\mathbf{V} = \nabla \times \mathbf{V}$, where $\mathbf{V} = \mathbf{V}(x, y, z)$ is a vector field. Describe, in words, what properties of the field \mathbf{V} are expressed by its *curl*.

(5 Marks)

- (e) Find the matrix products \mathbf{AB} and \mathbf{BA} , and hence show that $\mathbf{AB} \neq \mathbf{BA}$, when

$$\mathbf{A} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \text{ and } \mathbf{B} = \begin{bmatrix} 5 & 6 \\ 7 & 8 \end{bmatrix}.$$

(4 Marks)

- (f) By considering matrix determinants, determine the *rank* of the matrix

$$\mathbf{A} = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}.$$

(4 Marks)

QUESTION 1. IS CONTINUED ON NEXT PAGE

QUESTION 1 CONTINUED....

(g) The matrix $\mathbf{B} = \begin{bmatrix} 2 & 3 \\ 4 & 1 \end{bmatrix}$ has *eigenvalues* given by $\lambda_1 = -2$ and $\lambda_2 = 5$.

Hence, verify that:

- (i) the product of the eigenvalues of \mathbf{B} is equal to the value of the determinant of \mathbf{B} ; and
- (ii) the sum of the eigenvalues of \mathbf{B} is equal to the sum of the diagonal elements of \mathbf{B} .

(4 Marks)

(h) Use the *integrating factor method* to show that the general solution of

$\frac{dy}{dx} + py = q$, where p and q are constants, can be written as

$$y(x) = \frac{q}{p} + Ce^{-px},$$

where C is an arbitrary constant.

(5 Marks)

(i) Use the *chain rule* to show that $v = f(u)$ is a solution of the partial differential equation:

$$\frac{\partial v}{\partial x} + \frac{1}{c} \frac{\partial v}{\partial t} = 0,$$

when $u = x - ct$, c is a constant, and f is an arbitrary differentiable function.

(5 Marks)

SECTION B

2. An electrostatic charge distribution gives rise to a scalar potential given by:

$$\phi(x, y, z) = y^2 \sin x + xz^3 + 2z + 4y ,$$

where x , y , and z are space coordinates (physical units have been omitted for simplicity). Show that the associated vector field $\mathbf{E} = -\nabla\phi = -\text{grad}\phi$ is given by:

$$\mathbf{E}(x, y, z) = -(y^2 \cos x + z^3)\mathbf{i} - (2y \sin x + 4)\mathbf{j} - (3xz^2 + 2)\mathbf{k} .$$

(10 Marks)

Hence, prove that the original charge distribution density, given by

$$\rho = \epsilon_0 \nabla \cdot \mathbf{E} = \epsilon_0 \text{div } \mathbf{E} , \text{ is:}$$

$$\rho(x, y, z) = \epsilon_0 (y^2 - 2) \sin x - 6\epsilon_0 xz .$$

(10 Marks)

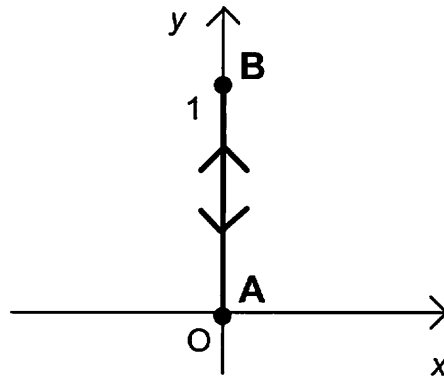
For the above vector field $\mathbf{E}(x, y, z)$, verify that $\oint_C \mathbf{E} \cdot d\mathbf{r} = 0$ by considering line

elements, $d\mathbf{r}$, along the closed path C (up and down the y -axis, in the $z = 0$ plane) defined as:

- (i) from point A at the origin, where $(x, y) = (0,0)$, to point B, where $(x, y) = (0,1)$,

and then

- (ii) from point B back to point A (see diagram below).



(10 Marks)

3. For a vector field $\mathbf{A}(x, y, z)$, Stokes' theorem can be stated as:

$$\int_S (\mathbf{curl} \mathbf{A}) \cdot d\mathbf{S} = \oint_C \mathbf{A} \cdot d\mathbf{r}.$$

Explain the meaning of each of the symbols used in this equation and the interpretation of the quantity $\mathbf{curl} \mathbf{A}$ that is implied by this theorem.

(8 marks)

For the particular vector field:

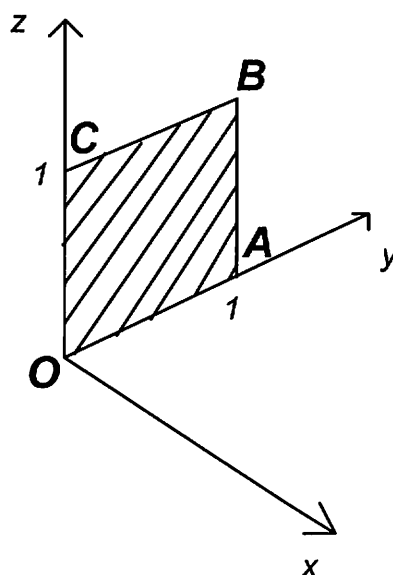
$$\mathbf{A}(x, y, z) = xy\mathbf{i} + (2y - xz)\mathbf{j} + xz\mathbf{k},$$

show that:

$$\mathbf{curl} \mathbf{A} = x\mathbf{i} - z\mathbf{j} - (x + z)\mathbf{k}.$$

(10 marks)

Hence, show that $\int_S (\mathbf{curl} \mathbf{A}) \cdot d\mathbf{S} = 0$ when S is the square area in the $x = 0$ plane whose corners are $O(0,0,0)$, $A(0,1,0)$, $B(0,1,1)$ and $C(0,0,1)$. This area is illustrated (shaded) in the figure below. In your calculation, assume that $d\mathbf{S}$ points in the *positive* x -direction.



(12 marks)

4. Answer **BOTH** parts of the question:

(a) Show that the *eigenvalues* of the matrix $\mathbf{A} = \begin{bmatrix} 8 & -2 \\ 4 & 2 \end{bmatrix}$ are given by

$$\lambda_1 = 4 \text{ and } \lambda_2 = 6.$$

(8 Marks)

Hence, find either one of the two linearly independent *eigenvectors* of the matrix \mathbf{A} .

(8 Marks)

(b) Use a method of your choice, to find the *inverse* of the matrix \mathbf{B} , where

$$\mathbf{B} = \begin{bmatrix} 1 & 0 & -1 \\ -2 & 1 & 0 \\ 1 & -1 & 2 \end{bmatrix}.$$

(14 Marks)

5. Answer **BOTH** parts of the question:

- (a) An electrical circuit consists of a resistance R and a capacitance C connected in series to a battery of constant voltage V . By considering the voltage dropped across R and C , one arrives at an ordinary differential equation for the charge stored $Q(t)$:

$$R \frac{dQ}{dt} + \frac{Q}{C} = V ,$$

where t is time. Show that the general solution of this differential equation is given by:

$$Q(t) = Q(0)e^{-t/RC} + VC(1 - e^{-t/RC}) .$$

Also find the particular solution when $Q(0) = 0$ and identify the long-term steady-state and transient components of this particular solution. Give a physical interpretation of your results.

(20 Marks)

- (b) Use the (partial differential equation) method of *separation of variables* to prove that a solution of $\frac{\partial u}{\partial x} = 4 \frac{\partial u}{\partial y}$ is given by $u(x, y) = K e^{c(4x+y)}$, where K and c are constants.

(10 Marks)

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Question No. 1

SOLUTION

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(a) $\vec{A} = 2\hat{i} + a\hat{j} + \hat{k}$, $\vec{B} = 4\hat{i} - 2\hat{j} - 2\hat{k}$

$$\vec{A} \cdot \vec{B} = (2\hat{i} + a\hat{j} + \hat{k}) \cdot (4\hat{i} - 2\hat{j} - 2\hat{k})$$

$$= 8 - 2a - 2 = 6 - 2a$$

4

Perpendicular when $\vec{A} \cdot \vec{B} = 0$ i.e. when $6 - 2a = 0$
i.e. when $a = 3$.

(b) $\vec{v} = \vec{w} \times \vec{r} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 4 & 3 & -1 \\ 2 & -6 & -3 \end{vmatrix}$

$$= \hat{i} \begin{vmatrix} 3 & -1 \\ -6 & -3 \end{vmatrix} - \hat{j} \begin{vmatrix} 4 & -1 \\ 2 & -3 \end{vmatrix} + \hat{k} \begin{vmatrix} 4 & 3 \\ 2 & -6 \end{vmatrix}$$

$$= \hat{i}(-9 - 6) - \hat{j}(-12 + 2) + \hat{k}(-24 - 6)$$

4

$$= -15\hat{i} + 10\hat{j} - 30\hat{k}$$

(c) $\text{div } \vec{V} = \vec{\nabla} \cdot \vec{V} = \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \cdot (V_x \hat{i} + V_y \hat{j} + V_z \hat{k})$

$$= \frac{\partial V_x}{\partial x} + \frac{\partial V_y}{\partial y} + \frac{\partial V_z}{\partial z} \text{ , when } \vec{V} = (V_x, V_y, V_z)$$

$\text{div } \vec{V}$ is the net outflow of flux of \vec{V} per unit volume (at a point). Equivalently, it is the volume density of 'sources' and 'sinks' of flux of \vec{V} .

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SOLUTION

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$$(d) \text{curl } \underline{V} = \nabla \times \underline{V} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{vmatrix} = \hat{i} \begin{vmatrix} \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_y & v_z \end{vmatrix} - \hat{j} \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial z} \\ v_x & v_z \end{vmatrix} + \hat{k} \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \\ v_x & v_y \end{vmatrix} \text{ etc.}$$

curl \underline{V} gives the 'circulation' of the field \underline{V} about each point. In other words, it gives the degree (and orientation) of 'twist/spin/rotation/vorticity' of the field.

4

$$(e) AB = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \begin{pmatrix} 5 & 6 \\ 7 & 8 \end{pmatrix} = \begin{pmatrix} 5+14 & 6+16 \\ 15+28 & 18+32 \end{pmatrix} = \begin{pmatrix} 19 & 22 \\ 43 & 50 \end{pmatrix}$$

$$BA = \begin{pmatrix} 5 & 6 \\ 7 & 8 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} = \begin{pmatrix} 5+18 & 10+24 \\ 7+24 & 14+32 \end{pmatrix} = \begin{pmatrix} 23 & 34 \\ 31 & 46 \end{pmatrix} = AB$$

(here, or in general)

4

$$(f) \begin{vmatrix} 0 & 1 \\ 0 & 0 \end{vmatrix} = (0 \times 0) - (1 \times 0) = 0 - 0 = 0 \quad \therefore \text{rank} < 2$$

while submatrix $\begin{bmatrix} 1 \end{bmatrix}$ can be found with non-zero determinant $(1 \times 1 = 1)$. $\therefore \text{rank} = 1$.

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SOLUTION

MARKS

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(g) $B = \begin{bmatrix} 2 & 3 \\ 4 & 1 \end{bmatrix}$ $\lambda_1 = -2, \lambda_2 = 5$ (given eigenvalues)

(i) $\det B = |B| = (2 \times 1 - 3 \times 4) = 2 - 12 = -10$

while $\lambda_1 \lambda_2 = (-2) \times (5) = -10$; (an example of a general result).

(ii) $\lambda_1 + \lambda_2 = -2 + 5 = 3$,

while "trace of B" is sum of diagonal elements.

4 Here, $\text{trace}(B) = 2 + 1 = 3$, also; (another general result).

(h) $\frac{dy}{dx} + py = q$ (p, q constants) : of standard form: $\frac{dy}{dx} + p(x)y = q(x)$

where $P(x) = p$
 $Q(x) = q$. Integrating factor = $e^{\int p dx} = e^{\int p dx} = e^{px}$

Multiply equation:

$e^{px} \frac{dy}{dx} + e^{px} py = e^{px} q$ to get: $\frac{d}{dx}(e^{px} y) = e^{px} q$

Integrate:

$\int e^{px} y = \int e^{px} q dx + C \Rightarrow e^{px} y = q \int e^{px} dx + C$

5 $\Rightarrow e^{px} y = \frac{q}{p} e^{px} + C \Rightarrow y = \frac{q}{p} + C e^{-px}$

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Question No. 1

SOLUTION

MARKS

TEXT

(i) $\frac{\partial v}{\partial x} + \frac{1}{c} \frac{\partial v}{\partial t} = 0$. Verify $v = f(u)$ is solution where $u = x - ct$.

$$\bullet \frac{\partial v}{\partial x} = \frac{\partial v}{\partial u} \cdot \frac{\partial u}{\partial x} \quad (\text{chain rule})$$

$$= \frac{\partial v}{\partial u} \cdot 1 \quad \left[\text{since } \frac{\partial u}{\partial x} = \frac{\partial}{\partial x} (x - ct) \right].$$

$$\bullet \frac{\partial v}{\partial t} = \frac{\partial v}{\partial u} \cdot \frac{\partial u}{\partial t} \quad (\text{chain rule})$$

$$= \frac{\partial v}{\partial u} \cdot (-c)$$

→ substitute into equation (left-hand-side):

$$\frac{\partial v}{\partial u} \cdot 1 + \frac{1}{c} \cdot \frac{\partial v}{\partial u} \cdot (-c) = \frac{\partial v}{\partial u} - \frac{\partial v}{\partial u} = 0$$

= RHS of equation

∴ we have proved this is a solution, without needing to ~~specific~~ specify the function "f".

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EXAMINATION SOLUTION SHEET

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Question No.

2

SOLUTION

MARKS

TEXT

$$\phi = y^2 \sin \kappa + \kappa z^3 + 2z + 4y$$

$$\nabla = \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} ; \nabla \phi = \hat{i} \frac{\partial \phi}{\partial x} + \hat{j} \frac{\partial \phi}{\partial y} + \hat{k} \frac{\partial \phi}{\partial z}$$

$$\text{where } \frac{\partial \phi}{\partial x} = y^2 \cos \kappa + z^3, \quad \frac{\partial \phi}{\partial y} = 2y \sin \kappa + 4,$$

$$\frac{\partial \phi}{\partial z} = 3\kappa z^2 + 2$$

$$\Rightarrow \vec{E} = -\nabla \phi = - \left\{ \hat{i} (y^2 \cos \kappa + z^3) + \hat{j} (2y \sin \kappa + 4) + \hat{k} (3\kappa z^2 + 2) \right\}$$

$$= -(y^2 \cos \kappa + z^3) \hat{i} - (2y \sin \kappa + 4) \hat{j} - (3\kappa z^2 + 2) \hat{k}$$

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$$\rho = \epsilon_0 \nabla \cdot \vec{E} = \epsilon_0 \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \cdot (E_x \hat{i} + E_y \hat{j} + E_z \hat{k})$$

$$= \epsilon_0 \left(\frac{\partial E_x}{\partial x} + \frac{\partial E_y}{\partial y} + \frac{\partial E_z}{\partial z} \right)$$

$$\text{where } \frac{\partial E_x}{\partial x} = \frac{\partial}{\partial x} \left\{ -(y^2 \cos \kappa + z^3) \right\} = -(y^2 (-\sin \kappa)) = +y^2 \sin \kappa$$

$$\frac{\partial E_y}{\partial y} = \frac{\partial}{\partial y} \left\{ -(2y \sin \kappa + 4) \right\} = -(2 \sin \kappa + 0) = -2 \sin \kappa$$

$$\frac{\partial E_z}{\partial z} = \frac{\partial}{\partial z} \left\{ -(3\kappa z^2 + 2) \right\} = -(6\kappa z + 0) = -6\kappa z$$

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SOLUTION

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$$\begin{aligned} \therefore \rho &= \epsilon_0 \nabla \cdot \vec{E} = \epsilon_0 \left\{ y^2 \sin x - 2 \sin x - 6xz \right\} \\ &= \epsilon_0 (y^2 - 2) \sin x - 6 \epsilon_0 xz. \end{aligned}$$

$$\vec{E} = -(y^2 \cos x + z^2) \hat{i} - (2yz \sin x + 4) \hat{j} + (3xz^2 + 2) \hat{k}$$

$$\vec{E}(z=0) = -y^2 \cos x \hat{i} - (2yz \sin x + 4) \hat{j} + 2 \hat{k}$$

$$\text{Here, } d\vec{r} = dx \hat{i} + dy \hat{j} = dy \hat{j} \quad (dx = dz = 0)$$

$$\begin{aligned} \vec{E} \cdot d\vec{r} &= (\vec{E}_x \hat{i} + \vec{E}_y \hat{j} + \vec{E}_z \hat{k}) \cdot (dy \hat{j}) \\ &= E_y dy \quad (\hat{j} \cdot \hat{j} = 1, \hat{i} \cdot \hat{j} = \hat{k} \cdot \hat{j} = 0) \end{aligned}$$

i

$$= -(2yz \sin x + 4) dy$$

$$\text{Also, } x=0 \Rightarrow \vec{E} \cdot d\vec{r} = -4 dy$$

$$\begin{aligned} \therefore \oint_C \vec{E} \cdot d\vec{r} &= \int_A^B \vec{E} \cdot d\vec{r} + \int_B^A \vec{E} \cdot d\vec{r} = \int_0^1 (-4) dy + \int_1^0 (-4) dy \\ &= -4[y]_0^1 + (-4) \cdot [y]_1^0 = -4 - 4 \cdot (-1) \\ &= -4 - 4 = 0. \end{aligned}$$

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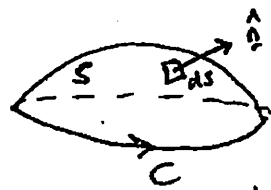
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SOLUTION

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$$\int_S (\text{curl } \vec{A}) \cdot d\vec{S} = \oint_C \vec{A} \cdot d\vec{r}$$



Surface integral over open surface S of dot product of $\text{curl } \vec{A} (= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix})$ and $d\vec{S}$ and closed line/curve integral along bounding curve C (clockwise sense with respect to \hat{n}) of dot product of \vec{A} and $d\vec{r}$ element (along C).

Projection of $\nabla \times \vec{A}$ gives surface density that integrates over S to give total circulation of \vec{A} around C .
 $\text{curl } \vec{A}$ measures circulation/rotation/vorticity ~~at~~ ^{around} a point.
 * [sufficient selection for full marks] *

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$$\vec{A} = xy\hat{i} + (2y - xz)\hat{j} + xz\hat{k} \equiv A_x\hat{i} + A_y\hat{j} + A_z\hat{k}$$

$$\nabla = \hat{i}\frac{\partial}{\partial x} + \hat{j}\frac{\partial}{\partial y} + \hat{k}\frac{\partial}{\partial z}$$

$$\begin{aligned} \nabla \times \vec{A} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix} = \hat{i} \begin{vmatrix} \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_y & A_z \end{vmatrix} - \hat{j} \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial z} \\ A_x & A_z \end{vmatrix} + \hat{k} \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \\ A_x & A_y \end{vmatrix} \\ &= \hat{i} \left(\frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) - \hat{j} \left(\frac{\partial A_z}{\partial x} - \frac{\partial A_x}{\partial z} \right) + \hat{k} \left(\frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) \end{aligned}$$

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SOLUTION

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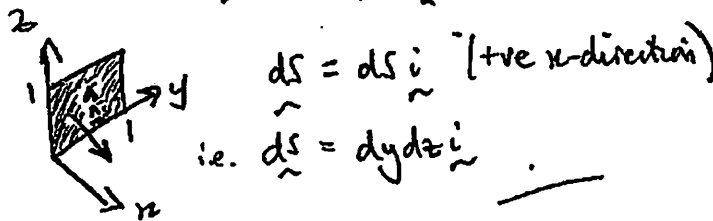
TEXT

where $\frac{\partial A_z}{\partial y} = \frac{\partial}{\partial y}(xz) = 0$, $\frac{\partial A_y}{\partial z} = \frac{\partial}{\partial z}(zy-xz) = -x$, $\frac{\partial A_x}{\partial z} = \frac{\partial}{\partial z}(xz) = z$,

$\frac{\partial A_x}{\partial z} = \frac{\partial}{\partial z}(xz) = 0$, $\frac{\partial A_y}{\partial x} = \frac{\partial}{\partial x}(zy-xz) = -z$, $\frac{\partial A_z}{\partial y} = \frac{\partial}{\partial y}(xy) = x$

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$\therefore \nabla \times \underline{A} = \hat{i} [0 - (-x)] - \hat{j} [z - 0] + \hat{k} [(-z) - x] = x\hat{i} - z\hat{j} - (x+z)\hat{k}$



(AND) on S, we have $x=0$, therefore

$\nabla \times \underline{A} = 0\hat{i} - z\hat{j} - (0+z)\hat{k} = -z\hat{j} - z\hat{k}$

$\therefore \int_S (\nabla \times \underline{A}) \cdot d\underline{S} = \int_S (-z\hat{j} - z\hat{k}) \cdot (\hat{i} dydz)$

$= \int_S (-z\hat{j} \cdot \hat{i} - z\hat{k} \cdot \hat{i}) dydz$

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$= \int_S 0 \cdot dydz = 0$

(NB Circulation could be calculated instead but this is longer)

NECESSARY

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SOLUTION

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$A = \begin{bmatrix} 8 & -2 \\ 4 & 2 \end{bmatrix}$ Eigenvalues are given by the characteristic equation: $\det(A - \lambda I) = 0$

Here, $\begin{vmatrix} 8-\lambda & -2 \\ 4 & 2-\lambda \end{vmatrix} = 0$

i.e. $(8-\lambda)(2-\lambda) + 8 = 0$

i.e. $16 - 2\lambda - 8\lambda + \lambda^2 + 8 = 0$

i.e. $\lambda^2 - 10\lambda + 24 = 0$

i.e. $\left. \begin{matrix} \lambda_1 + \lambda_2 = +10 \\ \lambda_1 \lambda_2 = 24 \end{matrix} \right\} \Rightarrow \begin{matrix} \lambda_1 = 4 \\ \lambda_2 = 6 \end{matrix}$

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Eigenvectors $\vec{x}_1 = \begin{pmatrix} x_1 \\ y_1 \end{pmatrix}$ and $\vec{x}_2 = \begin{pmatrix} x_2 \\ y_2 \end{pmatrix}$:

satisfy $\begin{pmatrix} 8-\lambda & -2 \\ 4 & 2-\lambda \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

FIND EITHER EIGENVECTOR...

$\lambda_1 = 4$

$\begin{pmatrix} 8-\lambda_1 & -2 \\ 4 & 2-\lambda_1 \end{pmatrix} \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ i.e. $\begin{matrix} (8-\lambda_1)x_1 - 2y_1 = 0 \\ 4x_1 + (2-\lambda_1)y_1 = 0 \end{matrix}$

i.e. $\begin{matrix} 4x_1 - 2y_1 = 0 \\ 4x_1 - 2y_1 = 0 \end{matrix}$ (since $\lambda_1 = 4$)

i.e. $2x_1 = y_1$

$\therefore \vec{x}_1 = \alpha \begin{pmatrix} 1 \\ 2 \end{pmatrix}$, α undetermined scalar.

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SOLUTION	
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8	<p>OR</p> <p>$\lambda_2 = 6$</p> $\begin{pmatrix} 8-\lambda_2 & -2 \\ 4 & 2-\lambda_2 \end{pmatrix} \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ <p>i.e. $(8-\lambda_2)x_2 - 2y_2 = 0$ $4x_2 + (2-\lambda_2)y_2 = 0$</p> <p>i.e. $2x_2 - 2y_2 = 0$ $4x_2 - 4y_2 = 0$ (since $\lambda_2 = 6$)</p> <p>i.e. $x_2 = y_2$</p> <p>$\therefore \underline{x_2} = \beta \begin{pmatrix} 1 \\ 1 \end{pmatrix}$,</p> <p>where β is an undetermined scalar.</p>

METHOD I (b)

$B = \begin{bmatrix} 1 & 0 & -1 \\ -2 & 1 & 0 \\ 1 & -1 & 2 \end{bmatrix}$. Consider $\left[\begin{array}{ccc|ccc} 1 & 0 & -1 & 1 & 0 & 0 \\ -2 & 1 & 0 & 0 & 1 & 0 \\ 1 & -1 & 2 & 0 & 0 & 1 \end{array} \right]$ and work on column 1 first.

$r_2 \rightarrow r_2 + 2r_1$
 $r_3 \rightarrow r_3 - r_1$ gives $\left[\begin{array}{ccc|ccc} 1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & -2 & 2 & 1 & 0 \\ 0 & -1 & 3 & -1 & 0 & 1 \end{array} \right]$ Now do column 2, $r_3 \rightarrow r_3 + r_2$ gives $\left[\begin{array}{ccc|ccc} 1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & -2 & 2 & 1 & 0 \\ 0 & 0 & 1 & 1 & 1 & 1 \end{array} \right]$

Finally, do column 3: $r_1 \rightarrow r_1 + r_3$ and $r_2 \rightarrow r_2 + 2r_3$ $\left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 2 & 1 & 1 \\ 0 & 1 & 0 & 4 & 3 & 2 \\ 0 & 0 & 1 & 1 & 1 & 1 \end{array} \right]$ i.e. $B^{-1} = \begin{bmatrix} 2 & 1 & 1 \\ 4 & 3 & 2 \\ 1 & 1 & 1 \end{bmatrix}$

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EXAMINATION SOLUTION CONTINUATION SHEET 3

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SOLUTION

MARKS METHOD II (alternative)

Inverse of $B = \begin{bmatrix} 1 & 0 & -1 \\ -2 & 1 & 0 \\ 1 & -1 & 2 \end{bmatrix}$ by the formal method: $B^{-1} = \frac{1}{|B|} C^T$

here $|B| = \begin{vmatrix} 1 & 0 \\ -1 & 2 \end{vmatrix} + 0 - \begin{vmatrix} -2 & 1 \\ 1 & -1 \end{vmatrix}$ (expanding along row 1)
 $= 2 - (2-1) = 1$

Matrix of cofactors $A_{11} = + \begin{vmatrix} 1 & 0 \\ -1 & 2 \end{vmatrix}$, $A_{12} = - \begin{vmatrix} -2 & 0 \\ 1 & 2 \end{vmatrix}$, $A_{13} = + \begin{vmatrix} -2 & 1 \\ 1 & -1 \end{vmatrix}$
 $= 2$ $= 4$ $= 1$

$A_{21} = - \begin{vmatrix} 0 & -1 \\ -1 & 2 \end{vmatrix}$, $A_{22} = + \begin{vmatrix} 1 & -1 \\ 1 & 2 \end{vmatrix}$, $A_{23} = - \begin{vmatrix} 1 & 0 \\ 1 & -1 \end{vmatrix}$
 $= 1$ $= 3$ $= 1$

$A_{31} = + \begin{vmatrix} 0 & -1 \\ 1 & 0 \end{vmatrix}$, $A_{32} = - \begin{vmatrix} 1 & -1 \\ -2 & 0 \end{vmatrix}$, $A_{33} = + \begin{vmatrix} 1 & 0 \\ -2 & 1 \end{vmatrix}$
 $= 1$ $= 2$ $= 1$

$\therefore B^{-1} = \frac{1}{1} C^T = \begin{pmatrix} 2 & 1 & 1 \\ 4 & 3 & 2 \\ 1 & 1 & 1 \end{pmatrix}$

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NECESSARY

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Question No.

5

SOLUTION

MARKS

$$\frac{dQ}{dt} + \left(\frac{1}{RC}\right)Q = \frac{V}{R}$$

$IF = e^{\frac{t}{RC} \int dt} = e^{\frac{t}{RC}}$. Now multiply equation

$$e^{\frac{t}{RC}} \frac{dQ}{dt} + \frac{e^{\frac{t}{RC}}}{RC} Q = e^{\frac{t}{RC}} \frac{V}{R}$$

$$\frac{d}{dt} \left[e^{\frac{t}{RC}} Q \right] = e^{\frac{t}{RC}} \cdot \frac{V}{R}$$

$$e^{\frac{t}{RC}} Q = \frac{V}{R} \cdot \left(\frac{1}{RC}\right) e^{\frac{t}{RC}} + A$$

i.e. $Q(t) = \frac{V}{R}(RC) + Ae^{-\frac{t}{RC}}$

(multiplying through
by $e^{-\frac{t}{RC}}$)

i.e. $Q(t) = VC + Ae^{-\frac{t}{RC}}$

Identify physical character of A

at $t=0$, $Q(0) = VC + A$

$\therefore A = Q(0) - VC$

\therefore General solution is $Q(t) = VC + [Q(0) - VC] e^{-\frac{t}{RC}}$

i.e. $Q(t) = VC + Q(0)e^{-\frac{t}{RC}} - VCe^{-\frac{t}{RC}}$

$\therefore Q(t) = Q(0)e^{-\frac{t}{RC}} + VC(1 - e^{-\frac{t}{RC}})$

(+15)

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 EXAMINATION SOLUTION CONTINUATION SHEET 1

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SOLUTION

MARKS
 (+5)
 → 20 submarks
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Particular solution Uncharged at $t=0$ i.e. $Q(0)=0$ since switch closed

$$\therefore Q(t) = VC(1 - e^{-t/\tau c})$$

$$-Q(t) = VC - VCe^{-t/\tau c}$$

steady-state transient i.e. $\rightarrow 0$ as $t \rightarrow \infty$

As $t \rightarrow \infty$, all voltage across C since voltage across R is IR

i.e. $\frac{dQ}{dt} R$ and requires time-varying charge.

$$\frac{\partial u}{\partial x} = 4 \frac{\partial u}{\partial y}$$

Separation of variables: $u = X(x)Y(y)$

gives $Y \lambda_x = 4XY_y$ (subscript denoting partial derivative)

i.e. $\frac{X_x}{4X} = \frac{Y_y}{Y} = c$ (separation constant)

Each equation can now be treated as an o.d.e. i.e. $\frac{dX}{dx} = 4cX$

and $\frac{dY}{dy} = cY$

Solutions are $X = Ae^{4cx}$, $Y = Be^{cy}$

A solution is thus $u = XY = Ke^{c(4x+y)}$, $K = AB$