

SAMPLE EXAM 3

SECTION A

1. Answer ALL parts of the question:

- (a) Determine the constant a such that the vectors $\mathbf{F} = 2\mathbf{i} + 2\mathbf{j} - \mathbf{k}$ and $\mathbf{r} = a\mathbf{i} - 7\mathbf{j} - 18\mathbf{k}$ are perpendicular.

(4 Marks)

- (b) The position of a moving particle is given by a time-dependent position vector $\mathbf{r}(t)$. Derive an expression for the velocity of the particle, $\mathbf{v}(t) = \frac{d\mathbf{r}(t)}{dt}$, when:

$$\mathbf{r}(t) = e^{-t} \mathbf{i} + 2 \cos(3t) \mathbf{j} + 2 \sin(3t) \mathbf{k}.$$

(4 Marks)

- (c) Describe what is meant by: (a) a *scalar field*; and (b) a *vector field*.
With reference to a typical weather forecast map, give one example of each type of field.

(6 Marks)

- (d) Describe the property of the vector field \mathbf{A} that $\text{div } \mathbf{A}$ (i.e. $\nabla \cdot \mathbf{A}$) represents (make reference to the divergence theorem and give one, or more, physical examples in your answer).

(5 Marks)

- (e) Describe the property of the vector field \mathbf{A} that $\text{curl } \mathbf{A}$ (i.e. $\nabla \times \mathbf{A}$) represents (make reference to Stokes' theorem and give one, or more, physical examples in your answer).

(5 Marks)

QUESTION A IS CONTINUED ON THE NEXT PAGE

- (f) By considering matrix determinants, show that the *rank* of the matrix \mathbf{A} is equal to 1 when:

$$\mathbf{A} = \begin{bmatrix} 2 & 6 \\ 3 & 9 \end{bmatrix}.$$

(4 Marks)

- (g) Relate your answer for part (c) to a description of the solution of the following two simultaneous equations:

$$2x + 6y = 1$$

$$3x + 9y = 2.$$

Illustrate your answer with a sketch that includes lines in the x - y plane.

(4 Marks)

- (h) Two simultaneous linear equations, with constant coefficients a , b , c and d , take the form:

$$ax + by = e$$

$$cx + dy = f$$

where e and f are also constants. Verify that the homogeneous system ($e = f = 0$) always has the trivial solution ($x = y = 0$).

(4 Marks)

- (i) Use the *chain rule* to show that $v = f(u)$ is a solution of the partial differential equation:

$$\frac{\partial v}{\partial x} + 3 \frac{\partial v}{\partial y} = 0,$$

where $u = y - 3x$ and f is an arbitrary differentiable function.

(4 Marks)

SECTION B

2. A particular scalar field is defined by the equation:

$$\phi(x, y, z) = x^2z + 2xy^2 + yz^2 .$$

Show that $\nabla\phi$ for this field is given by:

$$\nabla\phi = (2xz + 2y^2)\mathbf{i} + (4xy + z^2)\mathbf{j} + (x^2 + 2yz)\mathbf{k} .$$

(7 marks)

Hence, calculate the *magnitude* of the rate of change of $\phi(x, y, z)$ at the point $(x, y, z) = (1, 2, -1)$ in the direction of the vector $2\mathbf{i} + 3\mathbf{j} - 4\mathbf{k}$.

(13 marks)

Use the given form of $\nabla\phi$ (in terms of \mathbf{i} , \mathbf{j} , and \mathbf{k}) to prove that $\nabla\phi$ is a *conservative field*.

(10 marks)

3. Answer **BOTH** parts of the question:

(a) For a vector field $\mathbf{A}(x, y, z)$, Stokes' theorem can be stated as:

$$\int_S (\text{curl } \mathbf{A}) \cdot d\mathbf{S} = \oint_C \mathbf{A} \cdot d\mathbf{r}.$$

Explain the meaning of each of the symbols used in this equation and the interpretation of the quantity $\text{curl } \mathbf{A}$ that is implied by this theorem.

(8 Marks)

(b) The fluid velocity of a particular uniform flow is given by $\mathbf{V}_2 = 2\mathbf{i} + 3\mathbf{j} + \mathbf{k}$. An example of a non-uniform flow is given by $\mathbf{V}_3 = 2y\mathbf{i}$. Evaluate $\text{curl } \mathbf{V}$ for each of the flows \mathbf{V}_2 and \mathbf{V}_3 and interpret the results. What does *Stokes' theorem* imply regarding the character of the vector fields representing the uniform and the non-uniform flows?

(14 Marks)

The *circulation* of a vector field $\mathbf{V}(x, y, z) = V_x\mathbf{i} + V_y\mathbf{j} + V_z\mathbf{k}$ around a closed path C , can be written as: $\oint_C \mathbf{V} \cdot d\mathbf{r} = \oint_C V_x dx + V_y dy + V_z dz$. Hence, verify *Stokes' theorem* for the uniform flow \mathbf{V}_2 by considering the closed path C in the x - y plane (around the four sides of a square) given by:

$$(x, y, z) = (0, 0, 0) \rightarrow (0, 1, 0) \rightarrow (1, 1, 0) \rightarrow (1, 0, 0) \rightarrow (0, 0, 0).$$

(8 Marks)

4. Answer **BOTH** parts of the question:

(a) If

$$\mathbf{A} = \begin{bmatrix} 2 & -1 & -3 \\ 1 & 2 & 1 \\ 2 & -2 & -5 \end{bmatrix},$$

show that the *matrix of cofactors* of \mathbf{A} is:

$$\mathbf{C} = \begin{bmatrix} -8 & 7 & -6 \\ 1 & -4 & 2 \\ 5 & -5 & 5 \end{bmatrix}.$$

Show also that the determinant of \mathbf{A} is $\det(\mathbf{A}) = -5$. Hence, find the matrix \mathbf{A}^{-1} (that is the inverse of the matrix \mathbf{A}).

(15 Marks)

(b) Prove that the *eigenvalues* of the matrix $\mathbf{B} = \begin{bmatrix} 3 & 2 \\ 1 & 2 \end{bmatrix}$ are given by $\lambda_1 = 1$ and

$\lambda_2 = 4$. Hence, find *either one* of the two linearly independent *eigenvectors* of the matrix \mathbf{B} .

(15 Marks)

5. Answer **BOTH** parts of the question:

- (a) An electrical circuit consists of a resistance R and an inductance L connected in series to a battery of constant voltage V . The voltage dropped across R and L , and the current $I(t)$, are related through the ordinary differential equation:

$$L \frac{dI}{dt} + RI = V ,$$

where t is time.

Show that the general solution of this differential equation is given by:

$$I(t) = I(0) \exp\left[-\left(\frac{R}{L}\right)t\right] + \frac{V}{R} \left\{1 - \exp\left[-\left(\frac{R}{L}\right)t\right]\right\} .$$

Find the particular solution when $I(0) = 0$ and identify the long-term (steady-state) and transient components of this particular solution.

(18 Marks)

- (b) Use the method of *separation of variables* to prove that a solution of the partial differential equation $3 \frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} = 0$ is given by $u(x, y) = K e^{c(x-3y)}$, where K and c are constants.

(12 Marks)

SAMPLE EXAM 3 SOLUTIONS

EXAMINATION SOLUTION SHEET

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Paper Code:

Question No.

1

SOLUTION

MARKS

TEXT

4

$$1. (a) \underline{F} = 2\underline{i} + 2\underline{j} - \underline{k}, \quad \underline{r} = a\underline{i} - 7\underline{j} - 18\underline{k}$$

$$\therefore \underline{F} \cdot \underline{r} = (2a) + (2)(-7) + (-1)(-18)$$

$$= 2a - 14 + 18 = 2a + 4$$

$$\text{ie } \underline{F} \cdot \underline{r} = 0 \text{ when } 2a + 4 = 0 \text{ ie. when } a = -2.$$

4

$$1(b) \underline{r}(t) = e^{-t}\underline{i} + 2\cos 3t\underline{j} + 2\sin 3t\underline{k} \equiv (r_x(t), r_y(t), r_z(t))$$

$$\underline{v} = \frac{d\underline{r}}{dt} = \frac{dr_x}{dt}\underline{i} + \frac{dr_y}{dt}\underline{j} + \frac{dr_z}{dt}\underline{k}$$

$$\therefore \underline{v} = -e^{-t}\underline{i} + (-6\sin 3t)\underline{j} + 6\cos 3t\underline{k}.$$

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1(c) Scalar field \equiv region of space with unique scalar value associated with each point

Vector field \equiv as above, with vector value.

e.g. scalar: temperature, pressure,
vector: wind ~~speed~~ velocity

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EXAMINATION SOLUTION CONTINUATION SHEET

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Question No. 1

SOLUTION

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1(d) $\text{div } \vec{A} \equiv$ net volume density of sources and sinks of flux ("net outflow")

$$\int_V \text{div } \vec{A} dV = \oint_S \vec{A} \cdot d\vec{s}$$

$\underbrace{\int_V \text{div } \vec{A} dV}_{\text{volume density}} = \underbrace{\oint_S \vec{A} \cdot d\vec{s}}_{\text{net flux through closed surface } S}$

eg. \pm point charges \rightarrow E-flux,
lack of magnetic monopoles $\rightarrow \text{div } \vec{B} = 0$,
incompressible fluid with no sources/sinks $\rightarrow \text{div } \vec{v} = 0$

sufficient selection for full marks

5

1(e) $\text{curl } \vec{A} \equiv$ twist/swirl/rotation/vorticity/circulation about a point

$$\int_C \text{curl } \vec{A} \cdot d\vec{s} = \oint_C \vec{A} \cdot d\vec{r}$$

$\underbrace{\oint_C \vec{A} \cdot d\vec{r}}_{\text{circulation around } C}$

eg. electrostatics: $\nabla \times \vec{E} = 0$ (no vortices, conservative),
solenoid, current-carrying wire: loops/vortices in \vec{B} -field,
non-uniform fluid flow (paddlewheel), $\nabla \times \vec{v} \neq 0$,
tornadoes, hurricanes, plug-holes, fluid vortices...

sufficient selection for full marks

4

1(f) $A = \begin{bmatrix} 2 & 6 \\ 3 & 9 \end{bmatrix}$; $\begin{vmatrix} 2 & 6 \\ 3 & 9 \end{vmatrix} = 2 \cdot 9 - 6 \cdot 3 = 18 - 18 = 0$
 $\therefore \text{rank}(A) < 2$

Existence of one 1×1 submatrix with non-zero determinant is sufficient to give A a rank of 1.

For 1×1 matrices, determinant = element value.

Any of $\{2\}, \{6\}, \{3\}, \{9\}$ give non-zero determinant,
 $\therefore \text{rank}(A) = 1$.

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Paper Code:

Question No. 1

SOLUTION

MARKS

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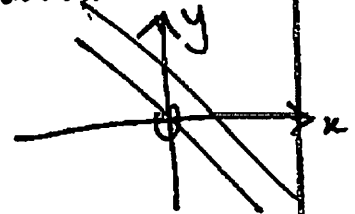
1(g) System is $A\underline{x} = \underline{b}$, where $A = \begin{bmatrix} 2 & 6 \\ 3 & 9 \end{bmatrix}$ and $|A| = 0$.

Augmented
coeff. matrix: $A_b = \begin{bmatrix} 2 & 6 & 1 \\ 3 & 9 & 2 \end{bmatrix}$ and, eg., $\begin{vmatrix} 6 & 1 \\ 9 & 2 \end{vmatrix} \neq 0$

$\Rightarrow \text{rank}(A_b) = 2$.

$\therefore \text{rank}(A) < \text{rank}(A_b) \Rightarrow$ no solution

Sketch: $y = -\frac{1}{3}x + \frac{1}{6}$
 $y = -\frac{1}{3}x + \frac{2}{9}$ } parallel lines
do not cross
 \rightarrow no solution



(sufficient amount of above for full marks)

4

2(h)

$ax + by = e = 0$
 $cx + dy = f = 0$

The trivial solution is $x = y = 0$.

Verify this general result by direct substitution:

$x = 0, y = 0$ gives

$a \cdot 0 + b \cdot 0 = 0$ ✓

$c \cdot 0 + d \cdot 0 = 0$ ✓

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EXAMINATION SOLUTION CONTINUATION SHEET

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Paper Code:

Question No. 1

SOLUTION

MARKS

TEXT

1(i)

$$v = f(u) \quad , \quad u = y - 3x \quad ,$$

$$\frac{\partial v}{\partial x} + 3 \frac{\partial v}{\partial y} = 0 \quad (*)$$

To show this (*),

$$\frac{\partial v}{\partial x} = \frac{\partial v}{\partial u} \frac{\partial u}{\partial x} = \frac{\partial v}{\partial u} \cdot (-3)$$

$$\frac{\partial v}{\partial y} = \frac{\partial v}{\partial u} \frac{\partial u}{\partial y} = \frac{\partial v}{\partial u} \cdot (1)$$

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$$\therefore \frac{\partial v}{\partial x} + 3 \frac{\partial v}{\partial y} = \frac{\partial v}{\partial u} \cdot (-3) + 3 \frac{\partial v}{\partial u} \cdot (1)$$

$$= -3 \frac{\partial v}{\partial u} + 3 \frac{\partial v}{\partial u} = 0$$

$\therefore v = f(u)$ is a solution (irrespective of the particular form of (arbitrarily differentiable) function f).

EXAMINATION SOLUTION SHEET

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Paper Code:	Question No. 2
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SOLUTION	
MARKS	TEXT
7	$\phi(x, y, z) = x^2z + 2xy^2 + yz^2$ $\nabla \equiv \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z}$ $\rightarrow \nabla \phi = \hat{i} \frac{\partial}{\partial x} (x^2z + 2xy^2 + yz^2) + \hat{j} \frac{\partial}{\partial y} (x^2z + 2xy^2 + yz^2) + \hat{k} \frac{\partial}{\partial z} (x^2z + 2xy^2 + yz^2)$ $= \hat{i} (2xz + 2y^2 + 0) + \hat{j} (0 + 4xy + z^2) + \hat{k} (x^2 + 0 + 2yz)$ $\therefore \nabla \phi = (2xz + 2y^2) \hat{i} + (4xy + z^2) \hat{j} + (x^2 + 2yz) \hat{k}$ <p style="margin-left: 20px;"><u>At point (1, 2, -1)</u></p> $\nabla \phi = (-2 + 8) \hat{i} + (8 + 1) \hat{j} + (1 - 4) \hat{k}$ $= 6 \hat{i} + 9 \hat{j} - 3 \hat{k}$ <p style="margin-left: 20px;">Direction derivative: $\frac{d\phi}{ds} = \nabla \phi \cdot \hat{u}$, where \hat{u} is a unit vector in the specified direction</p> <p style="margin-left: 20px;">In the direction of $2\hat{i} + 3\hat{j} - 4\hat{k}$,</p> $\hat{u} = \frac{2\hat{i} + 3\hat{j} - 4\hat{k}}{ 2\hat{i} + 3\hat{j} - 4\hat{k} }$ <p style="margin-left: 20px;">where $2\hat{i} + 3\hat{j} - 4\hat{k} = (2^2 + 3^2 + (-4)^2)^{\frac{1}{2}}$</p> $= (4 + 9 + 16)^{\frac{1}{2}} = \sqrt{29}$

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EXAMINATION SOLUTION CONTINUATION SHEET

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2

SOLUTION

MARKS

TEXT

13

$$\therefore \hat{u} = \frac{1}{\sqrt{29}} (2\hat{i} + 3\hat{j} - 4\hat{k})$$

$$\begin{aligned} \text{and } \frac{d\phi}{ds} &= \nabla\phi \cdot \hat{u} = (6\hat{i} + 9\hat{j} - 3\hat{k}) \cdot \frac{1}{\sqrt{29}} (2\hat{i} + 3\hat{j} - 4\hat{k}) \\ &= \frac{1}{\sqrt{29}} (12 + 27 + 12) \\ &= \frac{51}{\sqrt{29}} \end{aligned}$$

$$\text{Let } \underline{V} = \nabla\phi = V_x \hat{i} + V_y \hat{j} + V_z \hat{k},$$

$$\text{where } V_x = 2xz + 2y^2, V_y = 4xy + z^2, V_z = x^2 + 2yz$$

$$\nabla\phi \text{ conservative } \Leftrightarrow \nabla \times \underline{V} = \underline{0}$$

$$\text{where } \nabla \times \underline{V} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ V_x & V_y & V_z \end{vmatrix}$$

$$= \hat{i} \left[\frac{\partial V_z}{\partial y} - \frac{\partial V_y}{\partial z} \right] - \hat{j} \left[\frac{\partial V_z}{\partial x} - \frac{\partial V_x}{\partial z} \right] + \hat{k} \left[\frac{\partial V_y}{\partial x} - \frac{\partial V_x}{\partial y} \right]$$

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SOLUTION

MARKS

TEXT

$$\begin{aligned} \nabla \times \underline{V} &= \underline{i} \left[\frac{\partial}{\partial y} (x^2 + 2yz) - \frac{\partial}{\partial z} (4xy + z^2) \right] - \underline{j} \left[\frac{\partial}{\partial x} (x^2 + 2yz) - \frac{\partial}{\partial z} (2xz) \right] \\ &\quad + \underline{k} \left[\frac{\partial}{\partial x} (4xy + z^2) - \frac{\partial}{\partial y} (2xz) \right] \\ &= \underline{i} [2z - 2z] - \underline{j} [2x - 2x] + \underline{k} [4y - 4y] \\ &= 0\underline{i} + 0\underline{j} + 0\underline{k} = \underline{0} \quad (\text{for all } x, y, z) \end{aligned}$$

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$\therefore \nabla \phi = \underline{V}$ is a conservative vector field.

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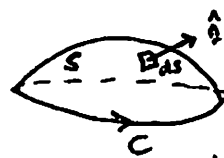
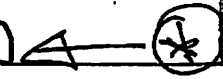
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EXAMINATION SOLUTION SHEET

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Paper Code: Question No. 3

SOLUTION	
MARKS	TEXT
8	<p>(a) $\int_S (\text{curl } \vec{A}) \cdot d\vec{S} = \oint_C \vec{A} \cdot d\vec{r}$</p>  <p>Surface integral over open surface S of dot product of $\text{curl } \vec{A} (= \dots)$ and $d\vec{S}$ and closed line/curve integral along bounding curve C (clockwise sense with respect to \hat{n}) of dot product of \vec{A} and $d\vec{r}$ element (along C).</p> <p>Projection of $\nabla \times \vec{A}$ gives surface density that integrates over S to give total circulation of \vec{A} around C</p> <p>$\text{curl } \vec{A}$ measures circulation/rotation/vorticity ^{around} a point</p> <p>[sufficient selection for full marks] \vec{A} </p>

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MARKS (5)

$\underline{v}_2 = 2\hat{i} + 3\hat{j} + h\hat{k}$ (a uniform flow)

$\underline{\nabla} \times \underline{v}_2 = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2 & 3 & h \end{vmatrix} = \hat{i}(0-0) - \hat{j}(0-0) + \hat{k}(0-0) = \underline{0}$
 \rightarrow Irrotational field (no circulation/vortices anywhere).

$\underline{v}_3 = 2y\hat{i}$

$\underline{\nabla} \times \underline{v}_3 = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2y & 0 & 0 \end{vmatrix} = \hat{i}(0-0) - \hat{j}(0-0) + \hat{k}(0-2) = -2\hat{k}$
 \rightarrow Rotational field (const. circulation/degree of rotation at each point).

Stokes' Theorem $\oint_C \underline{v} \cdot d\underline{r} = \int_S (\underline{\nabla} \times \underline{v}) \cdot d\underline{S}$

$\underline{\nabla} \times \underline{v}_2 = \underline{0} \Rightarrow \oint_C \underline{v}_2 \cdot d\underline{r} = 0$ (no circulation around any closed path)
 (- provided it's a simple path!)

also implies path independence of $\int_A^B \underline{v} \cdot d\underline{r}$ and other 'conservative' properties.

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$\oint_C \underline{v}_2 \cdot d\underline{r} = \oint_C v_x dx + v_y dy + v_z dz$
 $= \oint_C 2dx + 3dy + h dz$, using \underline{v}_2 .

$\therefore \oint_C \underline{v}_2 \cdot d\underline{r} = \int_0^1 3 dy + \int_0^1 2 dx + \int_0^0 3 dy + \int_1^0 2 dx$
 ($dx=0, dz=0$) ($dy=0, dz=0$) ($dx=0, dz=0$) ($dy=0, dz=0$)

$= \int_0^1 3 dy + \int_0^1 2 dx - \int_0^1 3 dy - \int_1^0 2 dx = 0$

(from above, $\underline{\nabla} \times \underline{v}_2 = \underline{0} \Rightarrow \int_S (\underline{\nabla} \times \underline{v}_2) \cdot d\underline{S} = 0$ and we have verified consistency with Stokes' theorem.)

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EXAMINATION SOLUTION SHEET

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SOLUTION

MARKS

TEXT

(a)

$$A = \begin{pmatrix} 2 & -1 & -3 \\ 1 & 2 & 1 \\ 2 & -2 & -5 \end{pmatrix}$$

Cofactors $A_{11} = + \begin{vmatrix} 2 & 1 \\ -2 & -5 \end{vmatrix} = -8$, $A_{12} = - \begin{vmatrix} 1 & 1 \\ 2 & -5 \end{vmatrix} = 7$, $A_{13} = + \begin{vmatrix} 1 & 2 \\ 2 & -2 \end{vmatrix} = -6$,

$$A_{21} = - \begin{vmatrix} -1 & -3 \\ -2 & -5 \end{vmatrix} = 1$$
, $A_{22} = + \begin{vmatrix} 2 & -3 \\ 2 & -5 \end{vmatrix} = -4$, $A_{23} = - \begin{vmatrix} 2 & -1 \\ 2 & -2 \end{vmatrix} = 2$,

$$A_{31} = + \begin{vmatrix} -1 & -3 \\ 2 & 1 \end{vmatrix} = 5$$
, $A_{32} = - \begin{vmatrix} 2 & -3 \\ 1 & 1 \end{vmatrix} = -5$, $A_{33} = + \begin{vmatrix} 2 & -1 \\ 1 & 2 \end{vmatrix} = 5$.

\therefore Matrix of cofactors, $C = \begin{pmatrix} A_{11} & A_{12} & A_{13} \\ A_{21} & A_{22} & A_{23} \\ A_{31} & A_{32} & A_{33} \end{pmatrix} = \begin{pmatrix} -8 & 7 & -6 \\ 1 & -4 & 2 \\ 5 & -5 & 5 \end{pmatrix}$

e.g. $|A| = 2A_{11} - 1 \cdot A_{12} - 3 \cdot A_{13}$ (along
bp row)
 $= -16 - 7 + 18 = -5$.

Then, $A^{-1} = \frac{1}{|A|} C^T = -\frac{1}{5} \begin{pmatrix} -8 & 1 & 5 \\ 7 & -4 & -5 \\ -6 & 2 & 5 \end{pmatrix} = \frac{1}{5} \begin{pmatrix} 8 & -1 & -5 \\ -7 & 4 & 5 \\ 6 & -2 & -5 \end{pmatrix}$

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EXAMINATION SOLUTION CONTINUATION SHEET

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SOLUTION

MARKS	TEXT
	<p>(b) $A = \begin{bmatrix} 3 & 2 \\ 1 & 2 \end{bmatrix}$ Eigenvalues</p> $ A - \lambda I = \begin{vmatrix} 3-\lambda & 2 \\ 1 & 2-\lambda \end{vmatrix}$ $= (3-\lambda)(2-\lambda) - 2 = 0$ <p>i.e. $6 - 2\lambda - 3\lambda + \lambda^2 - 2 = 0$ i.e. $\lambda^2 - 5\lambda + 4 = 0$</p> <p>By inspection, $\left. \begin{matrix} \lambda_1 + \lambda_2 = +5 \\ \lambda_1 \lambda_2 = 4 \end{matrix} \right\} \rightarrow \begin{matrix} \lambda_1 = 1 \\ \lambda_2 = 4 \end{matrix}$</p> <hr style="border-top: 1px dashed black;"/> <p><u>Eigenvectors</u> Since $A\vec{x} = \lambda\vec{x}$, these satisfy $A\vec{x} - \lambda I\vec{x} = \vec{0}$ i.e. $(A - \lambda I)\vec{x} = \vec{0}$ i.e. $\begin{pmatrix} 3-\lambda & 2 \\ 1 & 2-\lambda \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$</p> <p>Denote $\vec{x}_1 = \begin{pmatrix} x_1 \\ y_1 \end{pmatrix}$ as the eigenvector associated with λ_1.</p> <p>Then, $\begin{pmatrix} 3-\lambda_1 & 2 \\ 1 & 2-\lambda_1 \end{pmatrix} \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ i.e. $\begin{matrix} (3-\lambda_1)x_1 + 2y_1 = 0 \\ x_1 + (2-\lambda_1)y_1 = 0 \end{matrix}$ i.e. $\begin{matrix} (3-1)x_1 + 2y_1 = 0 \\ x_1 + (2-1)y_1 = 0 \end{matrix}$ (since $\lambda_1 = 1$)</p>

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SOLUTION

MARKS

TEXT

$$\text{i.e. } \left. \begin{aligned} 2x_1 + 2y_1 &= 0 \\ x_1 + y_1 &= 0 \end{aligned} \right\} \Rightarrow x_1 = -y_1$$

Eigenvectors are only defined in terms of the ratio of the components (to within an undetermined scalar)

$$\therefore \underline{x}_1 = \alpha \begin{pmatrix} -1 \\ 1 \end{pmatrix}, \quad \alpha = \text{undetermined scalar.}$$

OR

$$\begin{pmatrix} 3-\lambda & 2 \\ 1 & 2-\lambda \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

Denote $\underline{x}_2 = \begin{pmatrix} x_2 \\ y_2 \end{pmatrix}$ as the eigenvector associated with $\lambda_2 = 4$.

$$\text{Then, } \begin{pmatrix} 3-\lambda_2 & 2 \\ 1 & 2-\lambda_2 \end{pmatrix} \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \text{i.e. } \begin{aligned} (3-\lambda_2)x_2 + 2y_2 &= 0 \\ x_2 + (2-\lambda_2)y_2 &= 0 \end{aligned}$$

$$\text{i.e. } \begin{aligned} (3-4)x_2 + 2y_2 &= 0 \\ x_2 + (2-4)y_2 &= 0 \quad (\text{since } \lambda_2=4) \end{aligned}$$

$$\text{i.e. } \begin{aligned} -x_2 + 2y_2 &= 0 \\ x_2 - 2y_2 &= 0 \end{aligned}$$

Both equations imply $x_2 = 2y_2$.

$$\therefore \underline{x}_2 = \beta \begin{pmatrix} 2 \\ 1 \end{pmatrix}, \quad \text{where } \beta \text{ is an undetermined scalar.}$$

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EXAMINATION SOLUTION SHEET

These boxes MUST be completed

Paper Code:	Question No. 5
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SOLUTION

MARKS	TEXT
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a)

Standard form: $L \frac{dI}{dt} + RI = V \Rightarrow \frac{dI}{dt} + \left(\frac{R}{L}\right)I = \left(\frac{V}{L}\right)$

IF: $e^{\int \frac{R}{L} dt} = e^{\frac{R}{L}t} = e^{kt} \Rightarrow e^{kt} \frac{dI}{dt} + e^{kt} \left(\frac{R}{L}\right)I = e^{kt} \left(\frac{V}{L}\right)$

$\Rightarrow \frac{d}{dt} [e^{kt} \cdot I] = e^{kt} \cdot \left(\frac{V}{L}\right)$

$\Rightarrow e^{kt} \cdot I = \frac{V}{L} \int e^{kt} dt + C$

$= \frac{V}{L} \cdot \left(\frac{L}{R}\right) e^{kt} + C = \frac{V}{R} e^{kt} + C$

$\Rightarrow I(t) = \frac{V}{R} + C e^{-kt}$ after dividing by e^{kt} .

C can be identified by noting that at $t=0$, $I(0) = \frac{V}{R} + C e^0 = \frac{V}{R} + C$

$\rightarrow C = I(0) - \frac{V}{R} \rightarrow I(t) = \frac{V}{R} + \left(I(0) - \frac{V}{R}\right) e^{-kt} = \frac{V}{R} + I(0) e^{-kt} - \frac{V}{R} e^{-kt}$

ie. $I(t) = I(0) e^{-kt} + \frac{V}{R} (1 - e^{-kt})$

$I(t) = I(0) e^{-kt} + \frac{V}{R} (1 - e^{-kt})$

Particular solution when $I(0)=0$, ie switch closed at $t=0 \Rightarrow I=0$ at $t=0$,

$I(t) = 0 + \frac{V}{R} (1 - e^{-kt})$, $I(t) = \frac{V}{R} - \frac{V}{R} e^{-kt}$

(constant / steady-state) (time-varying, tends to zero, transient)

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Theoretical Physics I

EXAMINATION SOLUTION CONTINUATION SHEET

These boxes MUST be completed

Paper Code:

Question No. 5

SOLUTION

MARKS

TEXT

b)

$$3 \frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} = 0$$

Let $u(x,y) = X(x) \cdot Y(y)$ and substitute ...

$$3Y \frac{\partial X}{\partial x} + X \frac{\partial Y}{\partial y} = 0, \text{ rearrange as function of } x \text{ only, only}$$

$$\Rightarrow \frac{3}{X} \frac{\partial X}{\partial x} = -\frac{1}{Y} \frac{\partial Y}{\partial y}, \text{ introduce separation constant (c),}$$

$$\Rightarrow \frac{3}{X} \frac{\partial X}{\partial x} = c \Rightarrow \frac{3}{X} \frac{dX}{dx} = c \text{ and } -\frac{1}{Y} \frac{\partial Y}{\partial y} = c \Rightarrow \frac{dY}{dy} = -cY$$

i.e. p.d.e.s \rightarrow o.d.e.s (only one indep. var. in each)

$$\frac{dX}{dx} = \frac{c}{3} X$$

$$\int \frac{dX}{X} = \frac{c}{3} \int dx \text{ (ode sep. of vars)}$$

$$\ln X = \frac{c}{3} x + A$$

$$X = e^{\left(\frac{c}{3}x + A\right)}$$

$$\int \frac{dY}{Y} = -c \int dy$$

$$\Rightarrow \ln Y = -cy + B$$

$$\Rightarrow Y = e^{(-cy + B)}$$

A solution is then $u = XY = e^{\left(\frac{c}{3}x + A\right)} \cdot e^{(-cy + B)}$

$$= e^{\frac{c}{3}x - cy} \cdot e^{A+B}$$

$$= e^{c\left(\frac{x}{3} - y\right)} \cdot e^{A+B}$$

$$= e^{c\left(\frac{x}{3} - y\right)} \cdot e^{A+B}$$

$$\therefore u(x,y) = ke^{c\left(\frac{x}{3} - y\right)},$$

$$e^A = \frac{1}{3}$$

$$k = e^{A+B}$$

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