

TUTORIAL 2

This tutorial firstly deals with the divergence of a vector field \vec{A} :

$$\operatorname{div} \vec{A} = \nabla \cdot \vec{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}, \quad \text{where } \vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k},$$

and then returns to consider the curl of \vec{A} :

$$\operatorname{curl} \vec{A} = \nabla \times \vec{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix}.$$

The emphasis here is in the relationship between: the divergence and the flux $\int_S \vec{A} \cdot d\vec{S}$ through surfaces S , and the curl and its connection with the rotational character of the field (and hence the circulation $\oint_C \vec{A} \cdot d\vec{r}$).

The two main theorems that demonstrate these physical relations are:

the divergence theorem: $\int_V \nabla \cdot \vec{A} \, dV = \oint_S \vec{A} \cdot d\vec{S}$ (surface S enclosing volume V)

and Stokes's theorem: $\int_S (\nabla \times \vec{A}) \cdot d\vec{S} = \oint_C \vec{A} \cdot d\vec{r}$
(open surface S with bounding curve C)

Exercises

1. Which of the following vector fields have constant divergence?

(a) $\underline{V} = 3x\underline{i} + y\underline{j} + 2z\underline{k}$

(b) $\underline{V} = x^2\underline{i} + y^2\underline{j} + z^2\underline{k}$

(c) $\underline{V} = xy\underline{i} + yz\underline{j} + zx\underline{k}$

2. Determine the constant a for which \underline{V} has zero divergence,

where $\underline{V} = (x+3y)\underline{i} + (y-2z)\underline{j} + (x+az)\underline{k}$.

3. Determine the divergence of the following vector fields at the given point:

(a) $\underline{V} = xy^2\underline{i} - 2yz\underline{j} + xyz\underline{k}$ at point $(1, -1, 2)$

(b) $\underline{A} = x^2y\underline{i} + (xy+yz)\underline{j} + xz^2\underline{k}$ at point $(1, 2, 1)$

(c) $\underline{A} = xz\underline{i} - y^2\underline{j} + 2x^2y\underline{k}$ at point $(3, 2, 1)$

4. Show that the divergence of $\underline{V} = \frac{\underline{r}}{r^{3/2}}$ is $\frac{3}{2} \frac{1}{r^{3/2}}$,

where \underline{r} is a position vector and $r = |\underline{r}|$.

5. Determine which of the following vector fields are irrotational:

(a) $\underline{V} = 3x\underline{i} + 2y\underline{j} - 4z\underline{k}$

(b) $\underline{V} = x\underline{i} + 5xy\underline{j}$

(c) $\underline{A} = (4xy-z^3)\underline{i} + 2xz\underline{j} - 3xz^2\underline{k}$.

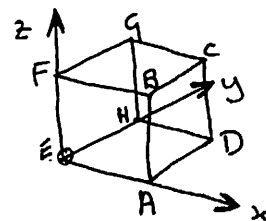
②

6. (a) Show that $\text{curl}(-y\underline{i} + x\underline{j})$ is a constant vector.

(b) Show that the vector field $yzi\underline{i} + zxj\underline{j} + xyk\underline{k}$ has zero divergence and zero curl. Interpret what these properties tell us about the character of this vector field.

③

7. The six planes $x=0, y=0, z=0, x=a, y=a, z=a$ form the faces of a cube of side a



In the above diagram, the corners of this cube are labelled as A, B, C, D, E, F and G.

If $\underline{A} = xi\underline{i} + yj\underline{j} + zk\underline{k}$, evaluate the flux of \underline{A} , namely $\int \underline{A} \cdot d\underline{S}$ through each of the six faces. Hence, determine the flux of \underline{A} through the entire surface of the cube.

8. Now, find the divergence of the vector field \underline{A} of the previous question and integrate it through the volume of the cube to verify the divergence theorem, i.e. that

$$\int_V \nabla \cdot \underline{A} \, dV = \oint_S \underline{A} \cdot d\underline{S}.$$

9. Repeat questions 7. and 8. for the vector field $\underline{A} = x\underline{i} + y\underline{j} + z\underline{k}$ and the cube of side $a=1$ that is bounded by the six planes $x=0, y=0, z=0, x=1, y=1$ and $z=1$.

10. Use the divergence theorem to show that if S is a closed surface enclosing a volume V then

$$\oint_S \underline{r} \cdot d\underline{S} = 5 \int_V r^2 dV,$$

where \underline{r} is a position vector and $r = |\underline{r}|$.

Hence, deduce the value of the surface integral $\oint_S \underline{A} \cdot d\underline{S}$

where

$$\underline{A} = (x^2 + y^2 + z^2)(x\underline{i} + y\underline{j} + z\underline{k})$$

and S is the surface of the cube bounded by $x=0, x=1, y=0, y=1, z=0$ and $z=1$.

11. Find $\nabla \cdot \underline{A}$ and $\nabla \times \underline{A}$ for the vector field

$$\underline{A} = (3x - 2y)\underline{i} + x^2z\underline{j} + (1 - 2z)\underline{k}.$$

For this vector field, evaluate

(a) $\int \underline{A} \cdot d\underline{S}$ over the circular region in the $z=0$ plane bounded by $x^2 + y^2 = a^2$. Count the area element as positive in the $+z$ -direction.

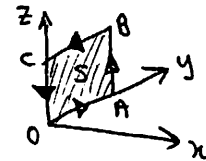
(4)

11. continued

(b) $\int (\nabla \times \underline{A}) \cdot d\underline{S}$ over the same region.

12. Consider the closed circuit OABCO defined with respect to Cartesian axes as:

$(0,0,0)$ to $(0,1,0)$ to $(0,1,1)$ to $(0,0,1)$ to $(0,0,0)$



If $\underline{A} = xy\underline{i} + (2y - xz)\underline{j} + xz\underline{k}$,

find $\text{curl } \underline{A}$.

Hence, find $\int (\nabla \times \underline{A}) \cdot d\underline{S}$ over the plane bounded by the above circuit. Consider $d\underline{S}$ as positive in the $+x$ -direction.

Now find the loop integral $\oint \underline{A} \cdot d\underline{r}$ round the circuit and check that your answers are consistent with Stokes' theorem.

[A further similar example appears in Stroud's

'Further Engineering Mathematics', p 726, Ex 2]

(5)

13. {Extract from Jan 2002 exam: "bookwork"} (5b)

FULL WORKED SOLUTIONS

(6)

Describe the property of a vector field \mathbf{A} that $\text{div } \mathbf{A} = \nabla \cdot \mathbf{A}$ expresses (make reference to the divergence theorem and give one, or more, physical examples in your answer).

Describe the property of a vector field \mathbf{A} that $\text{curl } \mathbf{A} = \nabla \times \mathbf{A}$ expresses (make reference to Stokes' theorem and give one, or more, physical examples in your answer).

Discuss the concept of *vector area* (making reference to the magnitude and to the direction of the cross product of two vectors in your answer).

(16 marks)

$$1. (a) \quad \underline{V} = 3x \underline{i} + y \underline{j} + 2z \underline{k} \equiv V_x \underline{i} + V_y \underline{j} + V_z \underline{k}$$

$$\text{div } \underline{V} = \nabla \cdot \underline{V} = \frac{\partial V_x}{\partial x} + \frac{\partial V_y}{\partial y} + \frac{\partial V_z}{\partial z}$$

(Recall that this is scalar - as a dot product should be)

$$= \frac{\partial (3x)}{\partial x} + \frac{\partial (y)}{\partial y} + \frac{\partial (2z)}{\partial z}$$

$$= 3 + 1 + 2 = 6$$

(i.e. independent of x, y, z and constant everywhere).

$$(b) \quad \underline{V} = x^2 \underline{i} + y^2 \underline{j} + z^2 \underline{k} \equiv V_x \underline{i} + V_y \underline{j} + V_z \underline{k}$$

$$\text{div } \underline{V} = \nabla \cdot \underline{V} = \frac{\partial V_x}{\partial x} + \frac{\partial V_y}{\partial y} + \frac{\partial V_z}{\partial z}$$

$$= \frac{\partial (x^2)}{\partial x} + \frac{\partial (y^2)}{\partial y} + \frac{\partial (z^2)}{\partial z}$$

$$= 2x + 2y + 2z = 2(x+y+z)$$

(i.e. given by a (scalar) function of x, y, z and not constant everywhere).

$$(c) \quad \underline{V} = xy \underline{i} + yz \underline{j} + zx \underline{k} \equiv V_x \underline{i} + V_y \underline{j} + V_z \underline{k}$$

$$\text{div } \underline{V} = \nabla \cdot \underline{V} = \frac{\partial V_x}{\partial x} + \frac{\partial V_y}{\partial y} + \frac{\partial V_z}{\partial z}$$

$$= \frac{\partial (xy)}{\partial x} + \frac{\partial (yz)}{\partial y} + \frac{\partial (zx)}{\partial z}$$

$$= y + z + x \quad (\text{not constant everywhere in } x, y, z)$$

2. $\vec{V} = (x+3y)\vec{i} + (y-2z)\vec{j} + (x+az)\vec{k}$, where a is constant

i.e. $\vec{V} \equiv V_x \vec{i} + V_y \vec{j} + V_z \vec{k}$

$$\begin{aligned} \operatorname{div} \vec{V} = \nabla \cdot \vec{V} &= \frac{\partial V_x}{\partial x} + \frac{\partial V_y}{\partial y} + \frac{\partial V_z}{\partial z} \\ &= \frac{\partial}{\partial x}(x+3y) + \frac{\partial}{\partial y}(y-2z) + \frac{\partial}{\partial z}(x+az) \\ &= 1 + 1 + a \\ &= 2+a. \end{aligned}$$

For zero divergence everywhere, we need $\nabla \cdot \vec{V} = 0$

i.e. $2+a=0$

i.e. $a = -2.$

3. (a) $\vec{V} = xy^2\vec{i} - 2yz\vec{j} + xyz\vec{k} \equiv V_x \vec{i} + V_y \vec{j} + V_z \vec{k}$

$$\begin{aligned} \operatorname{div} \vec{V} = \nabla \cdot \vec{V} &= \frac{\partial}{\partial x}(xy^2) + \frac{\partial}{\partial y}(-2yz) + \frac{\partial}{\partial z}(xyz) \\ &= y^2 - 2z + xy \end{aligned}$$

At point $(1, -1, 2)$, $x=1, y=-1, z=2$,

$$\begin{aligned} \therefore \nabla \cdot \vec{V} &= (-1)^2 - 2(2) + (1)(-1) \\ &= 1 - 4 - 1 = -4. \end{aligned}$$

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(b) $\vec{A} = (x^2y)\vec{i} + (xy+yz)\vec{j} + (xz^2)\vec{k}$

$$\begin{aligned} \nabla \cdot \vec{A} &= \frac{\partial}{\partial x}(x^2y) + \frac{\partial}{\partial y}(xy+yz) + \frac{\partial}{\partial z}(xz^2) \\ &= 2xy + x+z + 2xz \\ &= x(2y+1+2z) + z \end{aligned}$$

At point $(1, 2, 1)$, $x=1, y=2, z=1$,

$$\begin{aligned} \therefore \nabla \cdot \vec{A} &= 1(2 \cdot 2 + 1 + 2 \cdot 1) + 1 \\ &= 4 + 1 + 2 + 1 = 8. \end{aligned}$$

(c) $\vec{A} = xz\vec{i} - y^2\vec{j} + 2x^2y\vec{k}$

$$\begin{aligned} \nabla \cdot \vec{A} &= \frac{\partial}{\partial x}(xz) + \frac{\partial}{\partial y}(-y^2) + \frac{\partial}{\partial z}(2x^2y) \\ &= z - 2y \end{aligned}$$

At point $(3, 2, 1)$, $x=3, y=2, z=1$ but $\nabla \cdot \vec{A}$ does not depend on x , it only depends on y and z , and...

$$\nabla \cdot \vec{A} = 1 - 2(2) = 1 - 4 = -3.$$

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4. $\underline{V} = \frac{\underline{r}}{r^{3/2}}$, where \underline{r} is a position vector and $|\underline{r}| = r$.

If \underline{r} is a position vector, then $\underline{r} = x\underline{i} + y\underline{j} + z\underline{k}$
and $r = (x^2 + y^2 + z^2)^{1/2}$

$$\therefore \underline{V} = \frac{x\underline{i} + y\underline{j} + z\underline{k}}{r^{3/2}} = \frac{x\underline{i} + y\underline{j} + z\underline{k}}{(x^2 + y^2 + z^2)^{3/4}}$$

$$\left\{ \begin{aligned} r^{3/2} &= \left[(x^2 + y^2 + z^2)^{1/2} \right]^{3/2} \\ &= (x^2 + y^2 + z^2)^{3/4} \end{aligned} \right\}$$

ie. $\underline{V} = \frac{x}{(x^2 + y^2 + z^2)^{3/4}} \underline{i} + \frac{y}{(x^2 + y^2 + z^2)^{3/4}} \underline{j} + \frac{z}{(x^2 + y^2 + z^2)^{3/4}} \underline{k}$
 $= V_x \underline{i} + V_y \underline{j} + V_z \underline{k}$

$$\frac{\partial V_x}{\partial x} = \frac{\partial}{\partial x} \left[x(x^2 + y^2 + z^2)^{-3/4} \right] = (x^2 + y^2 + z^2)^{-3/4} + x \cdot \left(-\frac{3}{4} \right) (x^2 + y^2 + z^2)^{-7/4} \cdot 2x$$

└──────────────────┘
chain rule
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product rule

$$= \frac{(x^2 + y^2 + z^2)^{-4/4}}{(x^2 + y^2 + z^2)^{3/4}} - \frac{6x^2}{4} \cdot \frac{1}{(x^2 + y^2 + z^2)^{7/4}}$$

$$= \frac{x^2 + y^2 + z^2 - \frac{3}{2}x^2}{(x^2 + y^2 + z^2)^{7/4}}$$

$$= \frac{-\frac{1}{2}x^2 + y^2 + z^2}{(x^2 + y^2 + z^2)^{7/4}}$$

(9)

4. continued The symmetry of x, y, z then implies that

$$\frac{\partial V_y}{\partial y} = \frac{x^2 - \frac{1}{2}y^2 + z^2}{(x^2 + y^2 + z^2)^{7/4}}, \quad \frac{\partial V_z}{\partial z} = \frac{x^2 + y^2 - \frac{1}{2}z^2}{(x^2 + y^2 + z^2)^{7/4}}$$

$$\therefore \nabla \cdot \underline{V} = \frac{\partial V_x}{\partial x} + \frac{\partial V_y}{\partial y} + \frac{\partial V_z}{\partial z}$$

$$= \frac{\left(-\frac{1}{2}x^2 + y^2 + z^2 \right) + \left(x^2 - \frac{1}{2}y^2 + z^2 \right) + \left(x^2 + y^2 - \frac{1}{2}z^2 \right)}{(x^2 + y^2 + z^2)^{7/4}}$$

$$= \frac{3/2 (x^2 + y^2 + z^2)}{(x^2 + y^2 + z^2)^{7/4}}$$

$$= \frac{3/2}{(x^2 + y^2 + z^2)^{3/4}} = \frac{3}{2} \frac{1}{\left[(x^2 + y^2 + z^2)^{1/2} \right]^{3/2}}$$

$$\therefore \nabla \cdot \underline{V} = \frac{3}{2} \frac{1}{r^{3/2}}, \text{ since } r = (x^2 + y^2 + z^2)^{1/2}$$

5. *
* If a vector field is IRROTATIONAL then the
curl of this field is zero everywhere in this field *

(a) $\underline{V} = 3x\underline{i} + 2y\underline{j} - 4z\underline{k}$
 $= V_x \underline{i} + V_y \underline{j} + V_z \underline{k}$

(10)

5. (a) continued

$$\text{curl } \vec{V} = \nabla \times \vec{V} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ V_x & V_y & V_z \end{vmatrix}$$

$$\begin{aligned} \therefore \nabla \times \vec{V} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 3x & 2y & -4z \end{vmatrix} = \hat{i} \begin{vmatrix} \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2y & -4z \end{vmatrix} - \hat{j} \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial z} \\ 3x & -4z \end{vmatrix} \\ &\quad + \hat{k} \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \\ 3x & 2y \end{vmatrix} \\ &= \hat{i} \left[\frac{\partial}{\partial y}(-4z) - \frac{\partial}{\partial z}(2y) \right] - \hat{j} \left[\frac{\partial}{\partial x}(-4z) - \frac{\partial}{\partial z}(3x) \right] + \hat{k} \left[\frac{\partial}{\partial x}(2y) - \frac{\partial}{\partial y}(3x) \right] \\ &= \hat{i} [0 - 0] - \hat{j} [0 - 0] + \hat{k} [0 - 0] = \vec{0}. \end{aligned}$$

Since $\nabla \times \vec{V} = \vec{0}$ this vector field is irrotational.

(b) $\vec{V} = x\hat{i} + 5xy\hat{j} \equiv V_x\hat{i} + V_y\hat{j} + V_z\hat{k}$,

where $V_z = 0$ everywhere
(i.e. for all x, y, z)

(11)

5. (b) continued

$$\begin{aligned} \nabla \times \vec{V} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x & 5xy & 0 \end{vmatrix} = \hat{i} \begin{vmatrix} \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 5xy & 0 \end{vmatrix} - \hat{j} \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial z} \\ x & 0 \end{vmatrix} \\ &\quad + \hat{k} \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \\ x & 5xy \end{vmatrix} \\ &= \hat{i} \left[\frac{\partial}{\partial y}(0) - \frac{\partial}{\partial z}(5xy) \right] - \hat{j} \left[\frac{\partial}{\partial x}(0) - \frac{\partial}{\partial z}(x) \right] + \hat{k} \left[\frac{\partial}{\partial x}(5xy) - \frac{\partial}{\partial y}(x) \right] \\ &= \hat{i} [0 - 0] - \hat{j} [0 - 0] + \hat{k} [5y - 0] = 5y\hat{k}. \end{aligned}$$

$\therefore \nabla \times \vec{V}$ requires $y=0$ to be $\vec{0}$ and the vector field is not irrotational.

(c) $\vec{A} = (4xy - z^3)\hat{i} + 2x^2\hat{j} - 3xz^2\hat{k}$

$$\begin{aligned} \nabla \times \vec{A} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 4xy - z^3 & 2x^2 & -3xz^2 \end{vmatrix} = \hat{i} \begin{vmatrix} \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2x^2 & -3xz^2 \end{vmatrix} \\ &\quad - \hat{j} \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial z} \\ 4xy - z^3 & -3xz^2 \end{vmatrix} \\ &\quad + \hat{k} \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \\ 4xy - z^3 & 2x^2 \end{vmatrix} \end{aligned}$$

(12)

5. (c) continued

(13)

$$\begin{aligned} \therefore \nabla \times \vec{A} &= \hat{i} \left[\frac{\partial}{\partial y} (-3xz^2) - \frac{\partial}{\partial z} (2xz^2) \right] - \hat{j} \left[\frac{\partial}{\partial x} (-3xz^2) - \frac{\partial}{\partial z} (4xy - z^3) \right] \\ &\quad + \hat{k} \left[\frac{\partial}{\partial x} (2xz^2) - \frac{\partial}{\partial y} (4xy - z^3) \right] \\ &= \hat{i} [0 - 0] - \hat{j} [(-3z^2) - (-3z^2)] + \hat{k} [(4x) - (4x)] \\ &= \hat{i} \cdot 0 - \hat{j} \cdot 0 + \hat{k} \cdot 0 = \vec{0} \end{aligned}$$

\therefore This vector field \vec{A} is irrotational.

6. (a) To show that $\text{curl}(-y\hat{i} + x\hat{j})$ is a constant vector
 (b) To show that vector field $y z \hat{i} + z x \hat{j} + x y \hat{k}$ has zero divergence and zero curl. Interpret what these properties tell us about the character of this latter vector field.

Ans (a) Let $\vec{V} = -y\hat{i} + x\hat{j}$
 $= V_x \hat{i} + V_y \hat{j} + V_z \hat{k}$, where $V_x = -y$
 $V_y = x$
 $V_z = 0$

$$\nabla \times \vec{V} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -y & x & 0 \end{vmatrix} = \hat{i} \left[\frac{\partial}{\partial y} (0) - \frac{\partial}{\partial z} (x) \right] - \hat{j} \left[\frac{\partial}{\partial x} (0) - \frac{\partial}{\partial z} (-y) \right] + \hat{k} \left[\frac{\partial}{\partial x} (x) - \frac{\partial}{\partial y} (-y) \right]$$

6. (a) continued $\nabla \times \vec{V} = 0\hat{i} + 0\hat{j} + [(-1) - (-1)]\hat{k} = 2\hat{k}$ (14)

i.e. a constant vector $2\hat{k}$

i.e. no dependence on x, y, z

i.e. constant vector throughout x, y, z -space.

(b) $\vec{V} = yz\hat{i} + zx\hat{j} + xy\hat{k}$

$$\begin{aligned} \nabla \cdot \vec{V} &= \frac{\partial}{\partial x} (yz) + \frac{\partial}{\partial y} (zx) + \frac{\partial}{\partial z} (xy) \\ &= 0 + 0 + 0 = 0 \end{aligned}$$

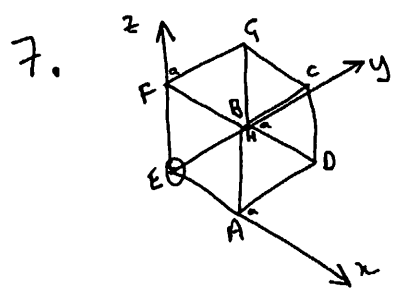
This implies no net 'outflow' of flux per unit volume anywhere in x, y, z -space i.e. there are no sources or sinks of flux anywhere.

$$\nabla \times \vec{V} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ yz & zx & xy \end{vmatrix} = \hat{i} \left[\frac{\partial}{\partial y} (xy) - \frac{\partial}{\partial z} (zx) \right] - \hat{j} \left[\frac{\partial}{\partial x} (xy) - \frac{\partial}{\partial z} (yz) \right] + \hat{k} \left[\frac{\partial}{\partial x} (zx) - \frac{\partial}{\partial y} (yz) \right]$$

6. (b) continued

$$\begin{aligned} \text{i.e. } \nabla \times \underline{V} &= \hat{i} [x-x] - \hat{j} [y-y] + \hat{k} [z-z] \\ &= 0\hat{i} + 0\hat{j} + 0\hat{k} = \underline{0} \end{aligned}$$

This implies that the vector field is irrotational i.e. there are no vortices in the field. We can also say that the field is conservative.



$$\underline{A} = x\hat{i} + y\hat{j} + z\hat{k}$$

We wish to find $\int \underline{A} \cdot d\underline{S}$ for each of the six sides.

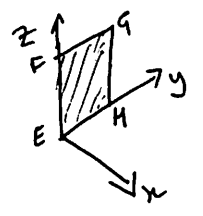
This is a closed surface so the $d\underline{S}$ vector for each surface will point outwards

Take each side in turn

- For this side, what is \underline{A} ?
- work out the direction of the unit vector \hat{n} such that $d\underline{S} = \hat{n} dS$
- work out $\underline{A} \cdot d\underline{S}$
- integrate over the side if $\underline{A} \cdot d\underline{S}$ is non-zero

(15)

7. continued



D_n EFGH, $x=0$ so $\underline{A} = y\hat{j} + z\hat{k}$
 \hat{n} points in the -ve x -direction (outwards and normal)

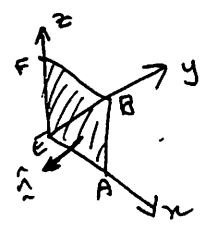
i.e. \hat{n} is $-\hat{i}$

$$\begin{aligned} \therefore \underline{A} \cdot d\underline{S} &= \underline{A} \cdot \hat{n} dS \\ &= (y\hat{j} + z\hat{k}) \cdot (-\hat{i}) dS \\ &= 0 \end{aligned}$$

$$\therefore \int_{EFGH} \underline{A} \cdot d\underline{S} = 0$$

(16)

D_n FBAE



Here, $y=0$ so $\underline{A} = x\hat{i} + y\hat{j} + z\hat{k}$
 becomes $\underline{A} = x\hat{i} + z\hat{k}$

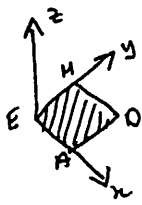
\hat{n} points in -ve y -direction

i.e. \hat{n} is $-\hat{j}$

$$\begin{aligned} \therefore \underline{A} \cdot d\underline{S} &= \underline{A} \cdot \hat{n} dS \\ &= (x\hat{i} + z\hat{k}) \cdot (-\hat{j}) dS \\ &= 0 \end{aligned}$$

$$\therefore \int_{FBAE} \underline{A} \cdot d\underline{S} = 0, \text{ too.}$$

7. continued On ADHE



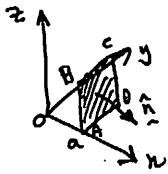
Here, $z=0$, $\vec{A} = x\vec{i} + y\vec{j}$ (17)

\hat{n} is $-\vec{k}$

$$\begin{aligned} \text{So, } \vec{A} \cdot d\vec{S} &= \vec{A} \cdot \hat{n} dS \\ &= (x\vec{i} + y\vec{j}) \cdot (-\vec{k}) dS \\ &= 0 \end{aligned}$$

$$\text{and } \int_{ADHE} \vec{A} \cdot d\vec{S} = 0$$

On ABCD



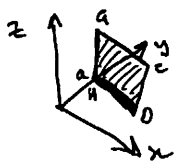
Here, $x=a$, $\vec{A} = a\vec{i} + y\vec{j} + z\vec{k}$, \hat{n} is \vec{i}

$$\begin{aligned} \text{So, } \vec{A} \cdot d\vec{S} &= (a\vec{i} + y\vec{j} + z\vec{k}) \cdot (\vec{i}) dS \\ &= (a\vec{i} \cdot \vec{i} + y\vec{j} \cdot \vec{i} + z\vec{k} \cdot \vec{i}) dS \\ &= (a + 0 + 0) dS = a dS \end{aligned}$$

$$\therefore \int_{ABCD} \vec{A} \cdot d\vec{S} = \int_{ABCD} a dS = a \int_{ABCD} dS = a \cdot a^2, \text{ since each side is a square of area } a^2$$

$$\therefore \int_{ABCD} \vec{A} \cdot d\vec{S} = a^3$$

On GCDH

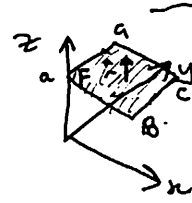


Here $y=a$, $\vec{A} = x\vec{i} + a\vec{j} + z\vec{k}$, \hat{n} is \vec{j}

$$\vec{A} \cdot d\vec{S} = \vec{A} \cdot \hat{n} dS = (x\vec{i} + a\vec{j} + z\vec{k}) \cdot \vec{j} dS$$

$$= a dS, \quad \int_{GCDH} \vec{A} \cdot d\vec{S} = a \int_{GCDH} dS = a^3 \text{ (as previously)}$$

7. continued On GCBF



Here, $z=a$, $\vec{A} = x\vec{i} + y\vec{j} + a^2\vec{k}$, \hat{n} is \vec{k}

$$\begin{aligned} \therefore \vec{A} \cdot d\vec{S} &= \vec{A} \cdot \hat{n} dS \\ &= (x\vec{i} + y\vec{j} + a^2\vec{k}) \cdot \vec{k} dS = a^2 dS \end{aligned}$$

$$\therefore \int_{GCBF} \vec{A} \cdot d\vec{S} = \int_{GCBF} a^2 dS = a^2 \int_{GCBF} dS = a^2 \cdot a^2 = a^4$$

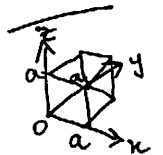
Total flux across whole cube is sum of the fluxes through the sides

$$\begin{aligned} \text{i.e. } \oint_{\text{cube}} \vec{A} \cdot d\vec{S} &= \int_{EFGH} + \dots + \int_{GCBF} \\ &= 0 + 0 + 0 + a^3 + a^3 + a^4 = 2a^3 + a^4 \end{aligned}$$

8. $\vec{A} = x\vec{i} + y\vec{j} + z^2\vec{k}$. Need to show: $\int_V \nabla \cdot \vec{A} dV = \int_S \vec{A} \cdot d\vec{S}$

$$\therefore \text{div } \vec{A} = \nabla \cdot \vec{A} = \frac{\partial}{\partial x}(x) + \frac{\partial}{\partial y}(y) + \frac{\partial}{\partial z}(z^2)$$

$$= 1 + 1 + 2z = 2 + 2z$$



$$\int_V \nabla \cdot \vec{A} dV = \int_V (2 + 2z) dV = \int_0^a \int_0^a \int_0^a (2 + 2z) dx dy dz$$

8. continued

$$\begin{aligned}
 \text{i.e. } \int_V \nabla \cdot \underline{A} dV &= \int_0^a \int_0^a [(2+2z)x]_0^a dy dz \\
 &= \int_0^a \int_0^a \{(2+2z)a - 0\} dy dz \\
 &= a \int_0^a \int_0^a (2+2z) dy dz \\
 &= a \int_0^a [(2+2z)y]_0^a dz \\
 &= a \int_0^a (2+2z)a dz \\
 &= a^2 \int_0^a (2+2z) dz = a^2 \left[2z + \frac{2z^2}{2} \right]_0^a \\
 &= a^2 \{2a + a^2 - 0\} = 2a^3 + a^4.
 \end{aligned}$$

Since question 7. gave $\int_S \underline{A} \cdot d\underline{S} = 2a^3 + a^4$, we have verified the divergence theorem for this example

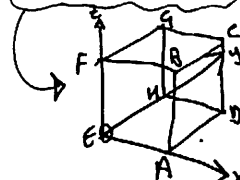
i.e. that $\int_V \nabla \cdot \underline{A} dV = \int_S \underline{A} \cdot d\underline{S}$.

9

As 7. with $a=1$

$$\underline{A} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$$

20



1) EFGH $x=0$, $\underline{A} = y\mathbf{j} + z\mathbf{k}$, $\hat{n} = -\mathbf{i}$
 $\underline{A} \cdot d\underline{S} = \underline{A} \cdot \hat{n} dS = 0 \therefore \int_{EFGH} \underline{A} \cdot d\underline{S} = 0$

2) FBAE $y=0$, $\underline{A} = x\mathbf{i} + z\mathbf{k}$, $\hat{n} = -\mathbf{j}$, $\underline{A} \cdot d\underline{S} = \underline{A} \cdot \hat{n} dS = (x\mathbf{i} + z\mathbf{k}) \cdot (-\mathbf{j}) dS = 0$
 $\therefore \int_{FBAE} \underline{A} \cdot d\underline{S} = 0$

3) ADHE $z=0$, $\underline{A} = x\mathbf{i} + y\mathbf{j}$, $\hat{n} = -\mathbf{k}$, $\underline{A} \cdot \hat{n} = (x\mathbf{i} + y\mathbf{j}) \cdot (-\mathbf{k}) = 0 \therefore \int_{ADHE} \underline{A} \cdot d\underline{S} = 0$

4) ABCD $x=1$, $\underline{A} = \mathbf{i} + y\mathbf{j} + z\mathbf{k}$, $\hat{n} = \mathbf{i}$, $\underline{A} \cdot \hat{n} = (\mathbf{i} + y\mathbf{j} + z\mathbf{k}) \cdot (\mathbf{i}) = 1$
 $\therefore \int_{ABCD} \underline{A} \cdot d\underline{S} = \int_{ABCD} \underline{A} \cdot \hat{n} dS = \int_{ABCD} (1) dS = \int_{ABCD} dS = 1$ (Area of each side is $1 \times 1 = 1$)

5) GCDH $y=1$, $\underline{A} = x\mathbf{i} + \mathbf{j} + z\mathbf{k}$, $\hat{n} = \mathbf{j}$, $\underline{A} \cdot \hat{n} = (x\mathbf{i} + \mathbf{j} + z\mathbf{k}) \cdot (\mathbf{j}) = 1$
 $\therefore \int_{GCDH} \underline{A} \cdot d\underline{S} = \int_{GCDH} \underline{A} \cdot \hat{n} dS = \int_{GCDH} (1) dS = 1$ (area of the side is 1)

6) GCBF $z=1$, $\underline{A} = x\mathbf{i} + y\mathbf{j} + \mathbf{k}$, $\hat{n} = \mathbf{k}$, $\underline{A} \cdot \hat{n} = (x\mathbf{i} + y\mathbf{j} + \mathbf{k}) \cdot (\mathbf{k}) = 1$
 $\therefore \int_{GCBF} \underline{A} \cdot d\underline{S} = \int_{GCBF} dS = 1$

Total flux, $\oint_S \underline{A} \cdot d\underline{S} = 0 + 0 + 0 + 1 + 1 + 1 = 3$.

$\int_V \text{div } \underline{A} dV$?

$\text{div } \underline{A} = \nabla \cdot \underline{A} = \frac{\partial}{\partial x}(x) + \frac{\partial}{\partial y}(y) + \frac{\partial}{\partial z}(z) = 1 + 1 + 1 = 3$

$\int_0^1 \int_0^1 \int_0^1 \text{div } \underline{A} dV = \int_0^1 \int_0^1 \int_0^1 3 dx dy dz = \int_0^1 [3x]_0^1 dy dz = \int_0^1 3 dy dz = \int_0^1 [3y]_0^1 dz = \int_0^1 3 dz = [3z]_0^1 = 3$

$\therefore \int_V \text{div } \underline{A} dV = \int_S \underline{A} \cdot d\underline{S}$ and div. theorem verified.

10. We wish to use $\int_S \underline{A} \cdot d\underline{S} = \int_V \text{div} \underline{A} \, dV$

to show that $\int_S r^2 \underline{r} \cdot d\underline{S} = 5 \int_V r^2 \, dV$

Comparing the left-hand sides, try setting $\underline{A} = r^2 \underline{r}$.

Then, by the divergence theorem $\text{div} \underline{A} = 5r^2$

If this is true, i.e. $\text{div} \underline{A} = 5r^2$, then we have used the

divergence theorem to prove that $\int_S r^2 \underline{r} \cdot d\underline{S} = 5 \int_V r^2 \, dV$.

Since \underline{r} is a position vector, $\underline{r} = x\underline{i} + y\underline{j} + z\underline{k}$
and $r^2 = x^2 + y^2 + z^2$.

$$\begin{aligned} \therefore \underline{A} = r^2 \underline{r} &= (x^2 + y^2 + z^2)(x\underline{i} + y\underline{j} + z\underline{k}) \\ &= (x^2 + y^2 + z^2)x\underline{i} + (x^2 + y^2 + z^2)y\underline{j} + (x^2 + y^2 + z^2)z\underline{k} \end{aligned}$$

i.e. $\underline{A} = A_x \underline{i} + A_y \underline{j} + A_z \underline{k}$

$$\text{div} \underline{A} = \nabla \cdot \underline{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}, \text{ where } \begin{cases} A_x = x^3 + xy^2 + xz^2 \\ A_y = x^2y + y^3 + yz^2 \\ A_z = x^2z + y^2z + z^3 \end{cases}$$

$$\left. \begin{aligned} \frac{\partial A_x}{\partial x} &= 3x^2 + y^2 + z^2 \\ \frac{\partial A_y}{\partial y} &= x^2 + 3y^2 + z^2 \\ \frac{\partial A_z}{\partial z} &= x^2 + y^2 + 3z^2 \end{aligned} \right\} \Rightarrow \nabla \cdot \underline{A} = 5x^2 + 5y^2 + 5z^2 = 5(x^2 + y^2 + z^2) = 5r^2, \text{ as required.}$$

(21)

10. continued. So we have $\int_S \underline{A} \cdot d\underline{S} = 5 \int_V r^2 \, dV$,

where $\underline{A} = r^2 \underline{r} = (x^2 + y^2 + z^2)(x\underline{i} + y\underline{j} + z\underline{k})$

You should realize now that the surface integral (flux) calculation can be much more work than the volume integral (see previous examples).

To work out $\int_S \underline{A} \cdot d\underline{S}$, where S is the surface of the cube with sides $x=0, y=0, z=0, x=1, y=1, z=1$,

work out instead $5 \int_0^1 \int_0^1 \int_0^1 r^2 \, dV$, where $r^2 = x^2 + y^2 + z^2$

$$\text{i.e. } 5 \int_0^1 \int_0^1 \int_0^1 (x^2 + y^2 + z^2) \, dx \, dy \, dz = 5 \int_0^1 \int_0^1 \left[\frac{x^3}{3} + y^2x + z^2x \right]_0^1 \, dy \, dz$$

$$= 5 \int_0^1 \int_0^1 \left[\frac{1}{3} + y^2 + z^2 \right] \, dy \, dz = 5 \int_0^1 \left[\frac{y}{3} + \frac{y^3}{3} + yz^2 \right]_0^1 \, dz$$

$$= 5 \int_0^1 \left[\frac{1}{3} + \frac{1}{3} + z^2 \right] \, dz = 5 \left[\frac{2z}{3} + \frac{z^3}{3} \right]_0^1$$

$$= 5 \left(\frac{1}{3} + \frac{1}{3} + \frac{1}{3} \right) = 5 \times 1 = 5.$$

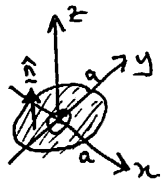
(22)

11. $\vec{A} = (3x-2y)\vec{i} + x^2z\vec{j} + (1-2z)\vec{k} \equiv A_x\vec{i} + A_y\vec{j} + A_z\vec{k}$ (23)

$$\vec{\nabla} \cdot \vec{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z} = 3 + 0 - 2 = 1$$

$$\begin{aligned} \vec{\nabla} \times \vec{A} &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 3x-2y & x^2z & 1-2z \end{vmatrix} = \vec{i} \begin{vmatrix} \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x^2z & 1-2z \end{vmatrix} - \vec{j} \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial z} \\ 3x-2y & 1-2z \end{vmatrix} + \vec{k} \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \\ 3x-2y & x^2z \end{vmatrix} \\ &= \vec{i} \left[\frac{\partial}{\partial y}(1-2z) - \frac{\partial}{\partial z}(x^2z) \right] - \vec{j} \left[\frac{\partial}{\partial x}(1-2z) - \frac{\partial}{\partial z}(3x-2y) \right] \\ &\quad + \vec{k} \left[\frac{\partial}{\partial x}(x^2z) - \frac{\partial}{\partial y}(3x-2y) \right] \\ &= \vec{i} [0 - x^2] - \vec{j} [0 - 0] + \vec{k} [2xz - (-2)] \end{aligned}$$

$$\therefore \vec{\nabla} \times \vec{A} = -x^2\vec{i} + 2(xz+1)\vec{k}$$



For this circular region, $z=0$.

$$\text{So, } \vec{A} = (3x-2y)\vec{i} + 0\vec{j} + (1-0)\vec{k}$$

$$\text{i.e. } \vec{A} = (3x-2y)\vec{i} + \vec{k}$$

Question states \hat{n} in positive z -direction, i.e. unit vector, $\hat{n} = \vec{k}$
 $\therefore d\vec{S} = \hat{n} dS = \vec{k} dS$

$$\begin{aligned} \text{i.e. } \vec{A} \cdot d\vec{S} &= [(3x-2y)\vec{i} + \vec{k}] \cdot \vec{k} dS \\ &= (3x-2y)\vec{i} \cdot \vec{k} dS + \vec{k} \cdot \vec{k} dS = 0 + dS \end{aligned}$$

$$\therefore \int_{\text{region}} \vec{A} \cdot d\vec{S} = \int_{\text{region}} dS = \pi a^2 \text{ (the area of the circular disk).}$$

11. continued (b) (24)

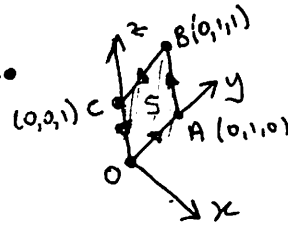
$$\vec{\nabla} \times \vec{A} = -x^2\vec{i} + 2(xz+1)\vec{k}$$

In same region, $z=0$. So, $\vec{\nabla} \times \vec{A} = -x^2\vec{i} + 2\vec{k}$

We still have $d\vec{S} = \vec{k} dS$.

$$\begin{aligned} \therefore \int_{\text{region}} (\vec{\nabla} \times \vec{A}) \cdot d\vec{S} &= \int_{\text{region}} (-x^2\vec{i} + 2\vec{k}) \cdot \vec{k} dS = \int_{\text{region}} 2 dS \\ &= 2 \int_{\text{region}} dS = 2 \times \pi a^2 = 2\pi a^2. \end{aligned}$$

12.



$$\vec{A} = xy\vec{i} + (2y-xz)\vec{j} + xz\vec{k}$$

$$\vec{\nabla} \times \vec{A} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ xy & 2y-xz & xz \end{vmatrix}$$

$$\text{i.e. } \vec{\nabla} \times \vec{A} = \vec{i} [0 - (-x)] - \vec{j} [z - 0] + \vec{k} [-z - x]$$

$$\text{i.e. } \vec{\nabla} \times \vec{A} = +x\vec{i} - z\vec{j} - (x+z)\vec{k}$$

For $\int_S (\vec{\nabla} \times \vec{A}) \cdot d\vec{S}$, we are told to take \hat{n} in +ve x -direction i.e. $\hat{n} = \vec{i}$

$$\therefore d\vec{S} = \hat{n} dS = \vec{i} dS$$

12. continued Don't forget to simplify $\nabla \times \underline{A}$!

On this surface, we have $x=0$.

$$\text{So, } \nabla \times \underline{A} = 0 \underline{i} - z \underline{j} - (0+z) \underline{k} = -z \underline{j} - z \underline{k}$$

$$\therefore \int_S (\nabla \times \underline{A}) \cdot d\underline{S} = \int_S (-z \underline{j} - z \underline{k}) \cdot \underline{i} dS = 0, \quad \begin{array}{l} \text{since } \underline{j} \cdot \underline{i} \\ = \underline{k} \cdot \underline{i} = 0 \end{array}$$

The loop integral

$$\oint_{OABCO} \underline{A} \cdot d\underline{r} = \oint_{OABCO} A_x dx + A_y dy + A_z dz$$

(i.e. $(A_x \underline{i} + A_y \underline{j} + A_z \underline{k}) \cdot (dx \underline{i} + dy \underline{j} + dz \underline{k})$)

where, in general, $A_x = xy$, $A_y = 2y - xz$, $A_z = xz$

$$\oint_{OABCO} \rightarrow \int_{OA} + \int_{AB} + \int_{BC} + \int_{CO}$$

Consider each part of the path separately

Along OA We have both $x=0$ and $z=0$

$$\therefore A_x=0, A_y=2y, A_z=0$$

We also only move along (i.e. change) y , so $dx=dz=0$

$$\therefore \int_{OA} A_x dx + A_y dy + A_z dz = \int_{OA} A_y dy = \int_0^1 2y dy = 2 \left[\frac{y^2}{2} \right]_0^1 = 1$$

(25)

12. continued

Along AB We have both $y=1$ and $x=0$

$$\therefore A_x=0, A_y=2, A_z=0$$

We also have that only dz is non-zero.

$$\text{So, } \int_{AB} A_x dx + A_y dy + A_z dz = \int_{AB} A_z dz = \int_{AB} 0 dz = 0$$

Along BC We have both $z=1$ and $x=0$.

$$\therefore A_x=0, A_y=2y, A_z=0$$

We also have that only dy is non-zero.

$$\begin{aligned} \text{So, } \int_{BC} A_x dx + A_y dy + A_z dz &= \int_{BC} A_y dy = \int_1^0 2y dy = - \int_0^1 2y dy \\ &= -2 \left[\frac{y^2}{2} \right]_0^1 = -1 \end{aligned}$$

Along CO We have both $y=0$ and $x=0$

$$\therefore A_x=0, A_y=0, A_z=0$$

$$\text{So, } \int_{CO} A_x dx + A_y dy + A_z dz = 0$$

$$\therefore \oint_{OABCO} = \int_{OA} + \int_{AB} + \int_{BC} + \int_{CO} = 1 + 0 - 1 + 0 = 0 \equiv \int_S (\nabla \times \underline{A}) \cdot d\underline{S}$$

consistent with Stokes' Theorem ✓

(26)

13.

div \vec{A} \equiv net volume density of sources and sinks of flux ("net outflow")

$$\int_V \text{div } \vec{A} dV = \oint_S \vec{A} \cdot d\vec{S}$$

(V) S
↑
volume density
↘
net flux through closed surface S

e.g. \pm point charges \rightarrow E-flux,
 lack of magnetic monopoles \rightarrow $\text{div } \vec{B} = 0$,
 incompressible fluid with no sources/sinks \rightarrow $\text{div } \vec{v} = 0$

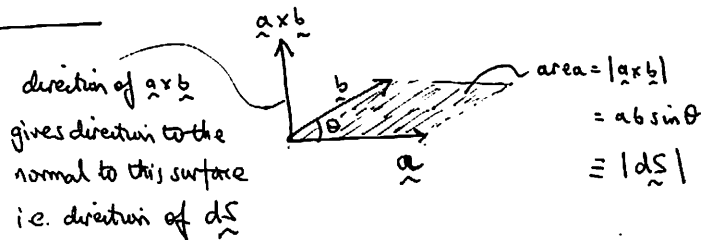
curl \vec{A} \equiv twist/swirl/rotation/vorticity/circulation about a point

$$\int_S \text{curl } \vec{A} \cdot d\vec{S} = \oint_C \vec{A} \cdot d\vec{s}$$

↘
circulation around C

e.g. electrostatics: $\nabla \times \vec{E} = 0$ (no vortices, conservative),
 solenoid, current-carrying wire: loops/vortices in \vec{B} -field,
 non-uniform fluid flow ("paddle wheel"), $\nabla \times \vec{v} \neq 0$,
 tornadoes, hurricanes, plug-holes, fluid vortices, ...

vector area



- could also mention conventions of:
- outward normals for a closed surface
 - clockwise sense of bounding curve C for elements normals on open surface.

* [A SUFFICIENT SELECTION OF ABOVE, UNDER EACH HEADING, FOR FULL MARKS] *